

A7L1D-J6 Wdg.412 - Technical Data Sheet

Standards

STAMFORD | AvK industrial alternators meet the requirements of the relevant parts of the IEC 60034 and the relevant sections of other international standards such as BS5000-3, ISO 8528-3, VDE 0530, NEMA MG1-32, CSA C22.2-100 and AS 60034. Other standards and certifications can be considered on request.

Quality Assurance

Alternators are manufactured using production procedures having a quality assurance level to BS EN ISO 9001.



Excitation and Voltage Regulators

Excitation System					
AVR Type	DECS150	DECS100	DM110		
Voltage Regulation	± 0.25%	± 0.25%	± 0.25%		with 4% Engine Governing
AVR Power	PMG	PMG	PMG		

No Load Excitation Voltage (V)	28.94 - 28.75
No Load Excitation Current (A)	1.09 - 1.08
Full Load Excitation Voltage (V)	95
Full Load Excitation Current (A)	3.6
Exciter Time Constant (seconds)	0.251

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Electrical Data								
Insulation System	H							
Stator Winding	Double Layer Concentric							
Winding Pitch	5/6							
Winding Leads	6							
Winding Number	412							
Number of Poles	6							
IP Rating	IP23							
RFI Suppression	BS EN 61000-6-2 & BS EN 61000-6-4,VDE 0875G, VDE 0875N. Refer to factory for others							
Waveform Distortion	NO LOAD < 1.5% NON-DISTORTING BALANCED LINEAR LOAD < 5.0%							
Short Circuit Ratio	1/Xd							
Steady State X/R Ratio	25.59							
50 Hz					60 Hz			
Telephone Interference	THF<2%				TIF<50			
Cooling Air Flow	2.07 m³/sec				2.48 m³/sec			
Voltage Star (V)	380	400	415	440	416	440	460	480
Voltage Parallel Star (V)	-	-	-	-	-	-	-	-
Voltage Delta (V)	-	-	-	-	-	-	-	-
kVA Base Rating (Class H) for Reactance Values (kVA)	1695	1750	1750	1600	1819	1925	2013	2100
Saturated Values in Per Unit at Base Ratings and Voltages								
Xd Dir. Axis Synchronous	2.34	2.18	2.03	1.65	2.52	2.38	2.28	2.18
X'd Dir. Axis Transient	0.20	0.18	0.17	0.14	0.21	0.20	0.19	0.18
X''d Dir. Axis Subtransient	0.15	0.14	0.13	0.11	0.17	0.16	0.15	0.14
Xq Quad. Axis Reactance	2.03	1.89	1.76	1.43	2.18	2.06	1.97	1.89
X''q Quad. Axis Subtransient	0.29	0.27	0.25	0.20	0.31	0.29	0.28	0.27
XL Stator Leakage Reactance	0.29	0.27	0.25	0.20	0.31	0.29	0.28	0.27
X2 Negative Sequence Reactance	0.23	0.22	0.20	0.16	0.25	0.24	0.23	0.22
X0 Zero Sequence Reactance	0.14	0.13	0.12	0.10	0.15	0.14	0.13	0.13
Unsaturated Values in Per Unit at Base Ratings and Voltages								
Xd Dir. Axis Synchronous	2.81	2.62	2.43	1.98	3.02	2.86	2.74	2.62
X'd Dir. Axis Transient	0.22	0.21	0.19	0.16	0.24	0.23	0.22	0.21
X''d Dir. Axis Subtransient	0.18	0.17	0.16	0.13	0.19	0.18	0.18	0.17
Xq Quad. Axis Reactance	2.09	1.95	1.81	1.47	2.25	2.12	2.03	1.95
X''q Quad. Axis Subtransient	0.35	0.32	0.30	0.24	0.37	0.35	0.34	0.32
XL Stator Leakage Reactance	0.32	0.30	0.28	0.23	0.35	0.33	0.31	0.30
Xlr Rotor Leakage Reactance	0.15	0.14	0.13	0.11	0.16	0.15	0.15	0.14
X2 Negative Sequence Reactance	0.28	0.26	0.24	0.20	0.30	0.28	0.27	0.26
X0 Zero Sequence Reactance	0.16	0.15	0.14	0.11	0.17	0.16	0.16	0.15

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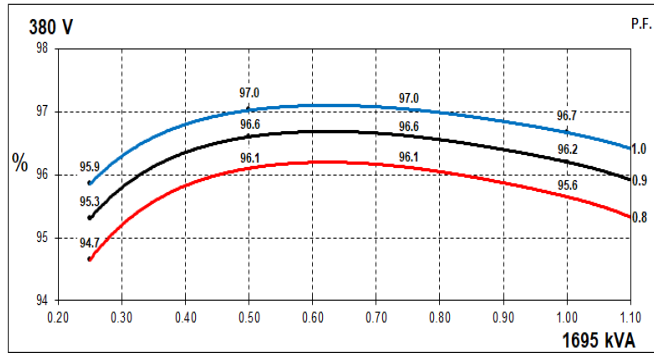
Time Constants (Seconds)		
T'd Transient Time Const.	0.144	
T''d Sub-Transient Time Const.	0.013	
T'do O.C. Field Time Const.	3.020	
Ta Armature Time Const.	0.031	
T''q Sub-Transient Time Const.	0.0240	
Resistances in Ohms (Ω) at 22 ⁰ C		
Stator Winding Resistance (Ra), per phase for series connected	0.00099	
Rotor Winding Resistance (Rf)	3.444	
Exciter Stator Winding Resistance	21	
Exciter Rotor Winding Resistance per phase	0.156	
PMG Phase Resistance (Rpmg) per phase	4.11	
Positive Sequence Resistance (R1)	0.0012	
Negative Sequence Resistance (R2)	0.0014	
Zero Sequence Resistance (R0)	0.0012	
Saturation Factors	400V	480V
SG1.0	0.233	0.233
SG1.2	1.263	1.263
Mechanical Data		
Shaft and Keys	All alternator rotors are dynamically balanced to better than ISO 21940-11 Grade 2.5 for minimum vibration in operation. Two bearing generators are balanced with a half key.	
	1 Bearing	2 Bearing
SAE Adaptor	SAE0,00	SAE0,00
Moment of Inertia	74.63 kgm ²	73.24 kgm ²
Weight Wound Stator	1214kg	1214kg
Weight Wound Rotor	1398kg	1398kg
Weight Complete Alternator	4255kg	4158kg
Shipping weight in a Crate	4314kg	4217kg
Packing Crate Size	220*115*155(cm)	220*115*155(cm)
Maximum Over Speed	1500 RPM for two minutes	
Bearing Drive End	-	BALL 6232
Bearing Non-Drive End	BALL 6319	BALL 6319

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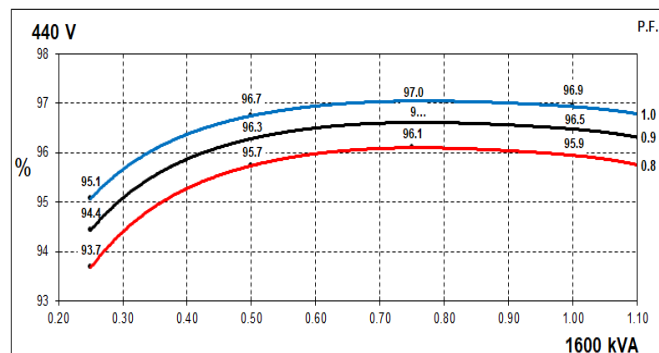
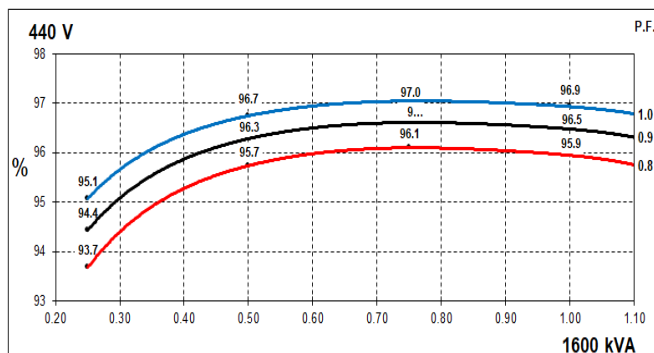
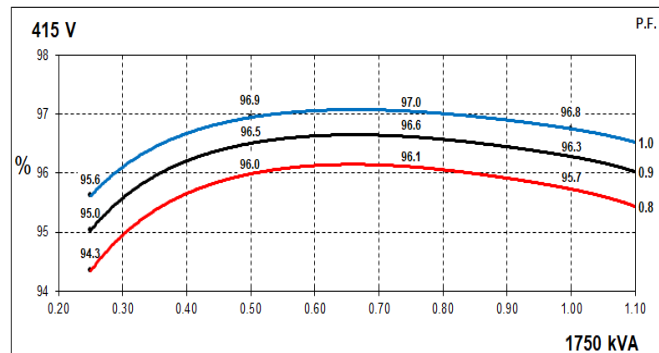
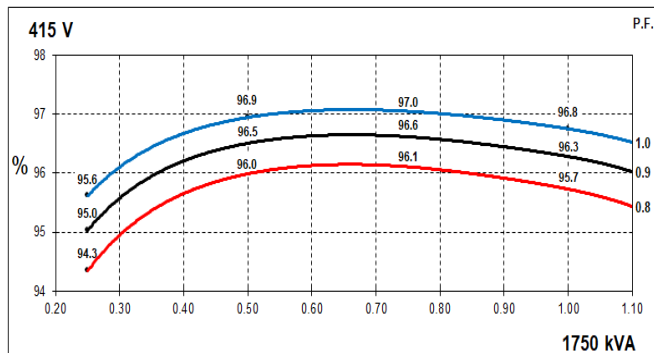
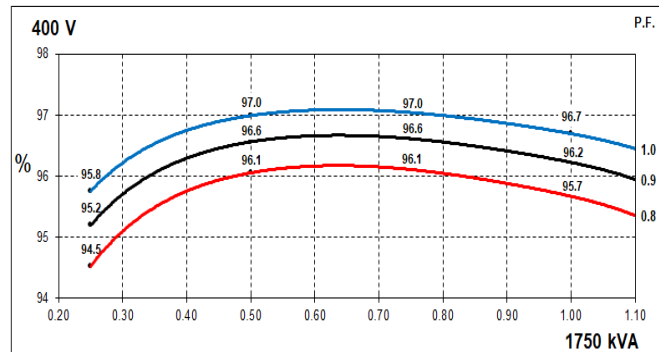
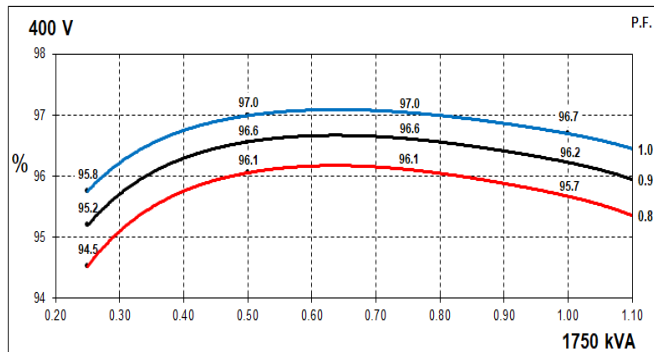
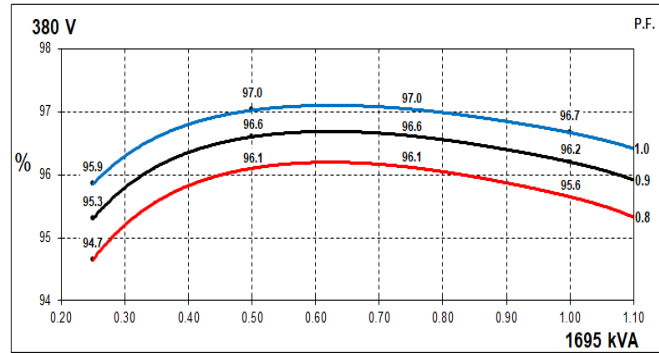
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THREE PHASE EFFICIENCY CURVES

50Hz



60Hz

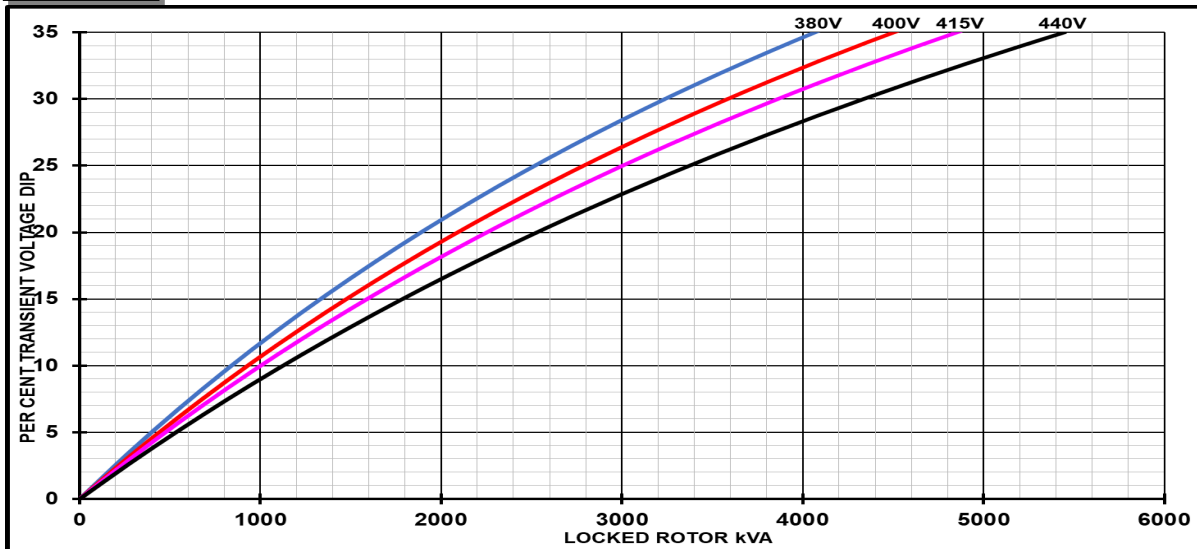


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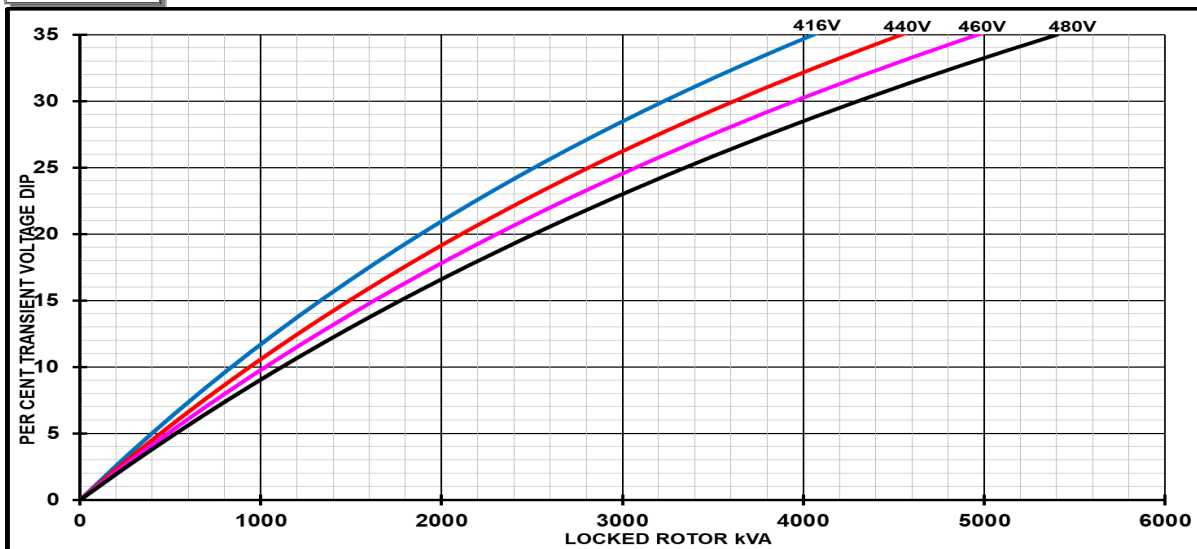
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Locked Rotor Motor Starting Curves - Separately Excited

50Hz



60Hz



Transient Voltage Dip Scaling Factor		Transient Voltage Rise Scaling Factor	
Lagging PF	Scaling Factor	Lagging PF	Scaling Factor
<= 0.4	1.00	<= 0.4	1.25
0.5	0.95	0.5	1.20
0.6	0.90	0.6	1.15
0.7	0.86	0.7	1.10
0.8	0.83	> 0.7	1.00
0.9	0.75		
0.95	0.70		
1	0.65		

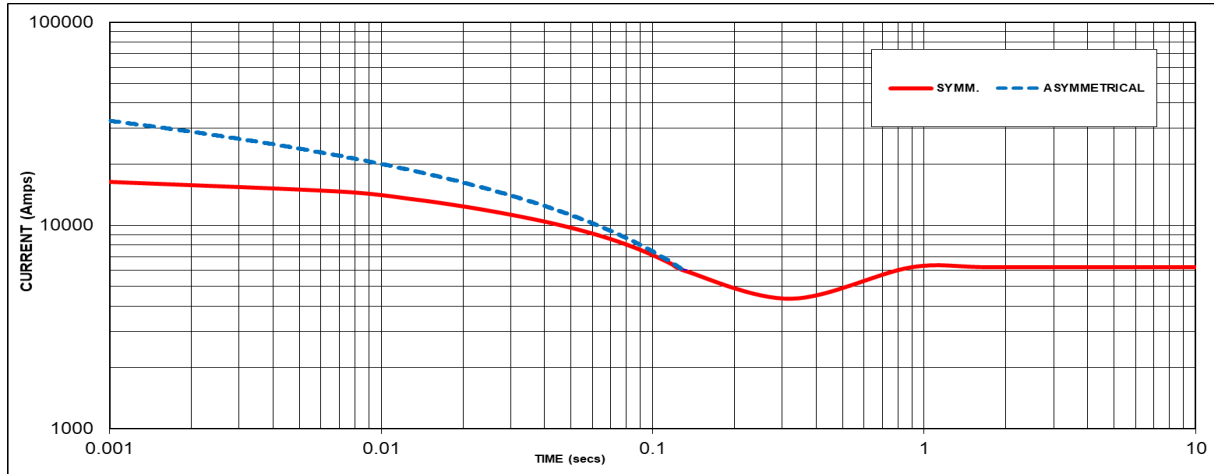
Note: To determine % Transient Voltage Dip or Voltage Rise at various PF, multiply the % Voltage Dip from the curve directly by the Scaling Factor.

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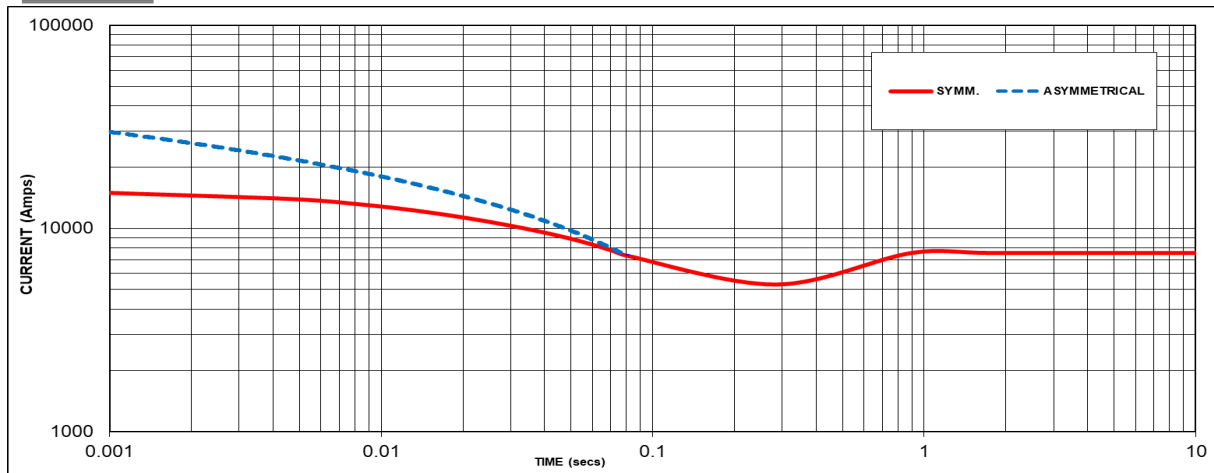
Three-phase Short Circuit Decrement Curve - Separately Excited

50Hz



Sustained Short Circuit = 6220 Amps

60Hz



Sustained Short Circuit = 7560 Amps

Note 1

The following multiplication factors should be used to adjust the values from curve between time 0.001 seconds and the minimum current point in respect of nominal operating voltage :

50Hz		60Hz	
Voltage	Factor	Voltage	Factor
380V	X 1.00	416V	X 1.00
400V	X 1.07	440V	X 1.06
415V	X 1.12	460V	X 1.12
440V	X 1.18	480V	X 1.17

The sustained current value is constant irrespective of voltage level

Note 2

The following multiplication factor should be used to convert the values calculated in accordance with NOTE 1 to those applicable to the various types of short circuit :

	3-phase	2-phase L-L	1-phase L-N
Instantaneous	x 1.00	x 0.87	x 1.30
Minimum	x 1.00	x 1.80	x 3.20
Sustained	x 1.00	x 1.50	x 2.50
Max. sustained duration	10 sec.	5 sec.	2 sec.

Note 3

All other times are unchanged

Curves are drawn for Star connections under no-load excitation at rated speeds. For other connection (where applicable) the following multipliers should be applied to current values as shown :

Parallel Star = Curve current value X 2

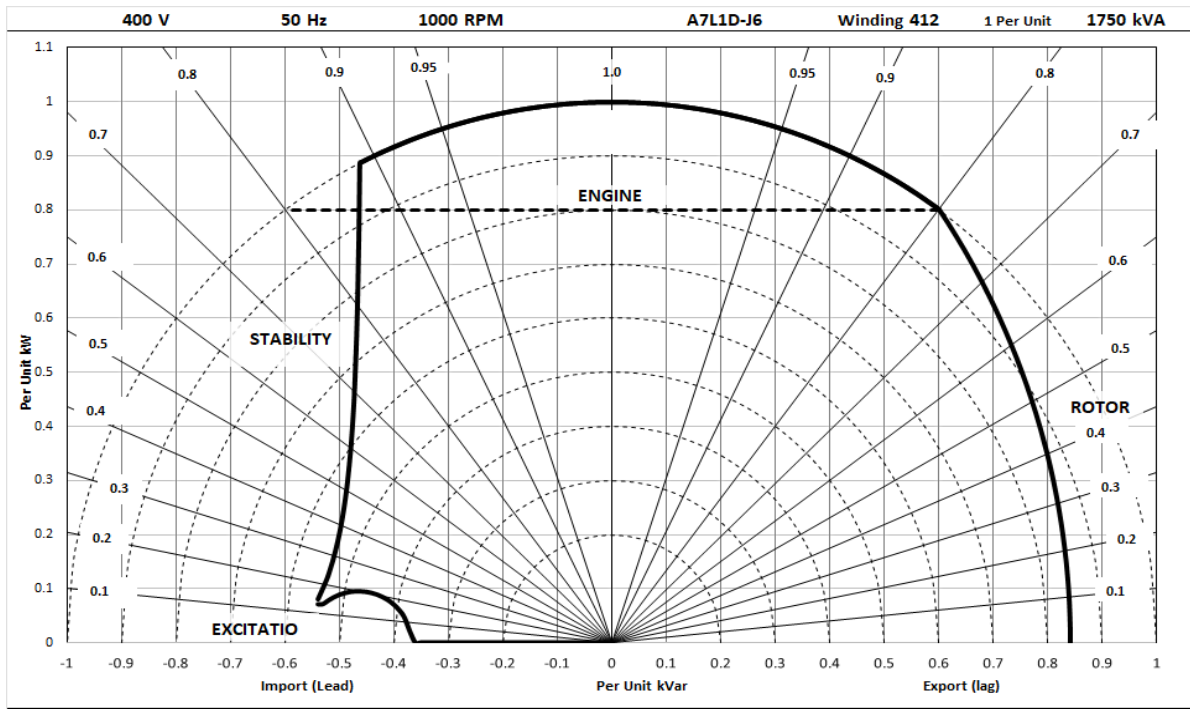
Series Delta = Curve current value X 1.732

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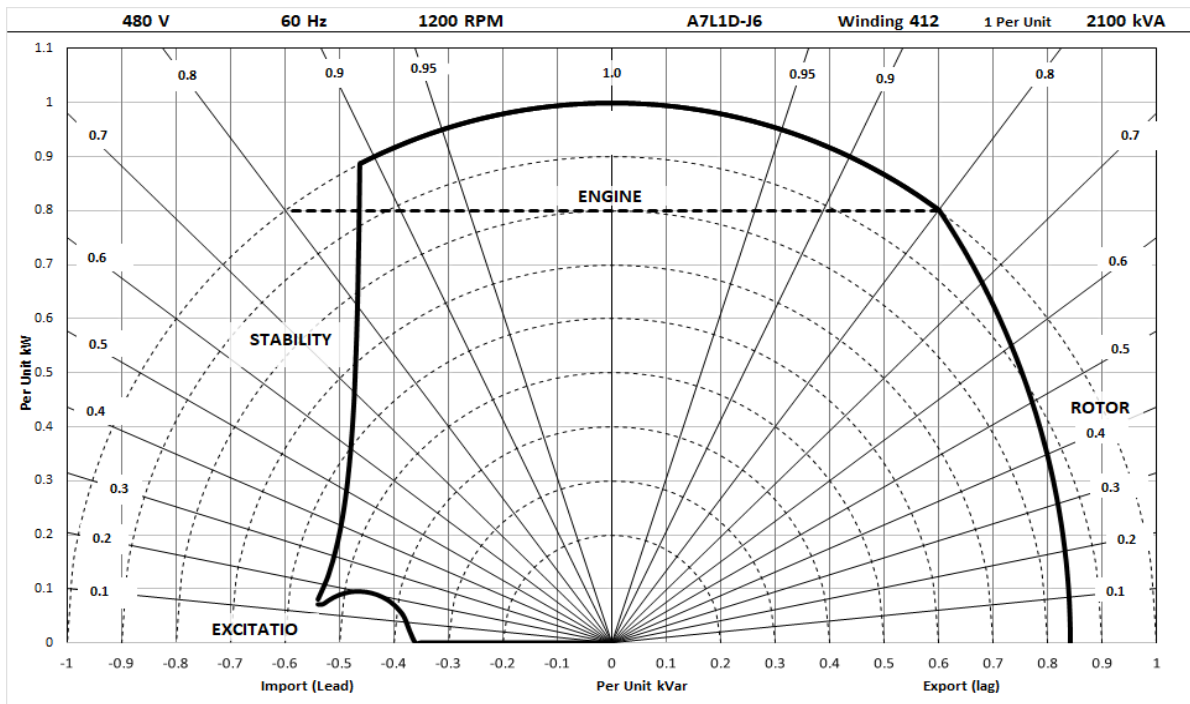
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Typical Alternator Operating Charts

400V/50Hz



480V/60Hz



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RATINGS AT 0.8 POWER FACTOR

Class - Temp Rise		Standby - 163/27°C				Standby - 150/40°C				Cont. H - 125/40°C				Cont. F - 105/40°C			
50 Hz	Star (V)	380	400	415	440	380	400	415	440	380	400	415	440	380	400	415	440
	Parallel Star (V)	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A
	Delta (V)	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A
	kVA	1820	1875	1875	1730	1770	1820	1820	1680	1695	1750	1750	1600	1530	1575	1575	1450
	kW	1456	1500	1500	1384	1416	1456	1456	1344	1356	1400	1400	1280	1224	1260	1260	1160
	Efficiency (%)	95.4	95.5	95.6	95.8	95.5	95.6	95.6	95.9	95.6	95.7	95.7	95.9	95.9	95.9	95.9	96.1
	kW Input	1526	1571	1570	1444	1482	1524	1522	1402	1418	1463	1462	1334	1277	1314	1313	1208

60 Hz	Star (V)	416	440	460	480	416	440	460	480	416	440	460	480	416	440	460	480
	Parallel Star (V)	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A
	Delta (V)	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A
	kVA	1963	2069	2156	2250	1894	2006	2094	2188	1819	1925	2013	2100	1638	1731	1806	1888
	kW	1570	1655	1725	1800	1515	1605	1675	1750	1455	1540	1610	1680	1310	1385	1445	1510
	Efficiency (%)	96.0	96.0	96.1	96.0	96.1	96.1	96.1	96.1	96.2	96.2	96.2	96.2	96.3	96.4	96.4	96.4
	kW Input	1635	1723	1796	1874	1577	1670	1743	1821	1513	1601	1674	1747	1360	1437	1499	1567

De-rates

All values tabulated above are subject to the following reductions:

- 5% when air inlet filters are fitted
- 3% for every 500 meters by which the operating altitude exceeds 1000 meters above mean sea level
- 3% for every 5°C by which the operational ambient temperature exceeds 40°C @ Class H temperature rise (please refer to applications for ambient temperature de-rates at other temperature rise classes)
- For marine alternators, 3% for every 5°C by which the operational ambient temperature exceeds 50°C
- For any other operating conditions impacting the cooling circuit please refer to applications

Note: Requirement for operating in an ambient exceeding 60°C and altitude exceeding 4000 meters (for <690V) or 1500 meters (for >690V) must be referred to applications.

Dimensional and Torsional Drawing

For dimensional and torsional information please refer to the alternator General Arrangement and rotor drawings available on our website (<http://stamford-avk.com/>)

Note: Continuous development of our products means that the information contained in our data sheets can change without notice, and specifications should always be confirmed with Cummins Generator Technologies prior to purchase.



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