



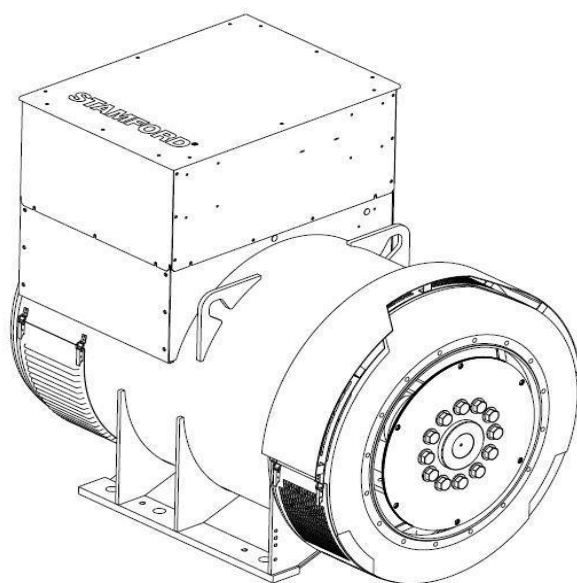
S7L1M-G4 Wdg.312 - Technical Data Sheet

Standards

STAMFORD industrial alternators meet the requirements of the relevant parts of the IEC 60034 and the relevant sections of other international standards such as BS5000-3, ISO 8528-3, VDE 0530, NEMA MG1-32, CSA C22.2-100 and AS 60034. Other standards and certifications can be considered on request.

Quality Assurance

Alternators are manufactured using production procedures having a quality assurance level to BS EN ISO 9001.



Excitation and Voltage Regulators

Excitation System					
AVR Type	MX322	DECS100	DECS150		
Voltage Regulation	± 0.5%	± 0.25%	± 0.25%		with 4% Engine Governing
AVR Power	PMG	PMG	PMG		

No Load Excitation Voltage (V)	15.4 - 14.7
No Load Excitation Current (A)	0.67 - 0.62
Full Load Excitation Voltage (V)	73
Full Load Excitation Current (A)	2.9
Exciter Time Constant (seconds)	0.125

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Electrical Data								
Insulation System	H							
Stator Winding	Double Layer Concentric							
Winding Pitch	2/3							
Winding Leads	6							
Winding Number	312							
Number of Poles	4							
IP Rating	IP23							
RFI Suppression	BS EN 61000-6-2 & BS EN 61000-6-4, VDE 0875G, VDE 0875N. Refer to factory for others							
Waveform Distortion	NO LOAD < 1.5% NON-DISTORTING BALANCED LINEAR LOAD < 5.0%							
Short Circuit Ratio	1/Xd							
Steady State X/R Ratio	27.72							
50 Hz					60 Hz			
Telephone Interference	THF<2%				TIF<50			
Cooling Air Flow	2.39 m³/sec				2.87 m³/sec			
Voltage Star (V)	380	400	415	440	416	440	460	480
Voltage Parallel Star (V)	-	-	-	-	-	-	-	-
Voltage Delta (V)	-	-	-	-	-	-	-	-
kVA Base Rating (Class H) for Reactance Values (kVA)	1780	1830	1830	1800	1991	2200	2244	2288
Saturated Values in Per Unit at Base Ratings and Voltages								
Xd Dir. Axis Synchronous	2.26	2.09	1.95	1.70	2.53	2.50	2.33	2.18
X'd Dir. Axis Transient	0.16	0.15	0.14	0.12	0.18	0.18	0.17	0.15
X''d Dir. Axis Subtransient	0.11	0.10	0.10	0.08	0.12	0.12	0.11	0.11
Xq Quad. Axis Reactance	1.70	1.57	1.46	1.28	1.90	1.88	1.75	1.64
X''q Quad. Axis Subtransient	0.19	0.18	0.17	0.15	0.22	0.21	0.20	0.19
XL Stator Leakage Reactance	0.07	0.06	0.06	0.05	0.08	0.08	0.07	0.07
X2 Negative Sequence Reactance	0.14	0.13	0.12	0.11	0.16	0.15	0.14	0.14
X0 Zero Sequence Reactance	0.03	0.03	0.03	0.02	0.03	0.03	0.03	0.03
Unsaturated Values in Per Unit at Base Ratings and Voltages								
Xd Dir. Axis Synchronous	2.71	2.51	2.33	2.04	3.03	3.00	2.80	2.62
X'd Dir. Axis Transient	0.18	0.17	0.16	0.14	0.21	0.20	0.19	0.18
X''d Dir. Axis Subtransient	0.13	0.12	0.11	0.10	0.14	0.14	0.13	0.13
Xq Quad. Axis Reactance	1.75	1.62	1.51	1.32	1.96	1.93	1.80	1.69
X''q Quad. Axis Subtransient	0.23	0.21	0.20	0.17	0.26	0.26	0.24	0.22
XL Stator Leakage Reactance	0.08	0.07	0.07	0.06	0.09	0.09	0.08	0.08
Xlr Rotor Leakage Reactance	0.18	0.17	0.15	0.13	0.20	0.20	0.18	0.17
X2 Negative Sequence Reactance	0.17	0.16	0.14	0.13	0.19	0.19	0.17	0.16
X0 Zero Sequence Reactance	0.04	0.03	0.03	0.03	0.04	0.04	0.04	0.03

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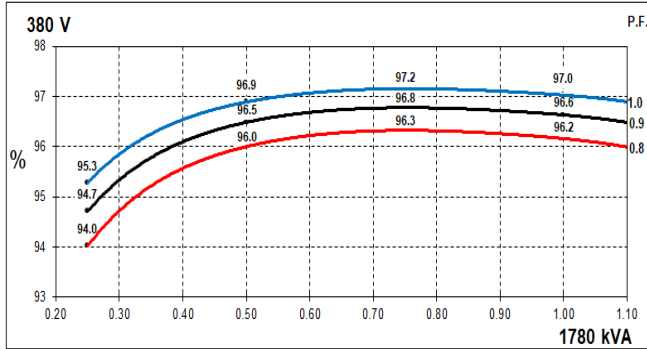
Time Constants (Seconds)		
T'd Transient Time Const.	0.150	
T''d Sub-Transient Time Const.	0.015	
T'do O.C. Field Time Const.	4.490	
Ta Armature Time Const.	0.028	
T''q Sub-Transient Time Const.	0.0104	
Resistances in Ohms (Ω) at 22 ⁰ C		
Stator Winding Resistance (Ra), per phase for series connected	0.00068	
Rotor Winding Resistance (Rf)	2.15	
Exciter Stator Winding Resistance	22.3	
Exciter Rotor Winding Resistance per phase	0.065	
PMG Phase Resistance (Rpmg) per phase	1.91	
Positive Sequence Resistance (R1)	0.0009	
Negative Sequence Resistance (R2)	0.0010	
Zero Sequence Resistance (R0)	0.0009	
Saturation Factors	400V	480V
SG1.0	0.283	0.275
SG1.2	1.366	1.201
Mechanical Data		
Shaft and Keys	All alternator rotors are dynamically balanced to better than ISO 21940-11 Grade 2.5 for minimum vibration in operation. Two bearing generators are balanced with a half key.	
	1 Bearing	2 Bearing
SAE Adaptor	SAE0 , 00	SAE0 , 00
Moment of Inertia	45.47 kgm²	44.44 kgm²
Weight Wound Stator	1725kg	1725kg
Weight Wound Rotor	1488kg	1445kg
Weight Complete Alternator	3637kg	3604kg
Shipping weight in a Crate	3689kg	3656kg
Packing Crate Size	220 X 105 X 155(cm)	220 X 105 X 155(cm)
Maximum Over Speed	2250 RPM for two minutes	
Bearing Drive End	-	BALL. 6232
Bearing Non-Drive End	BALL. 6319	BALL. 6319

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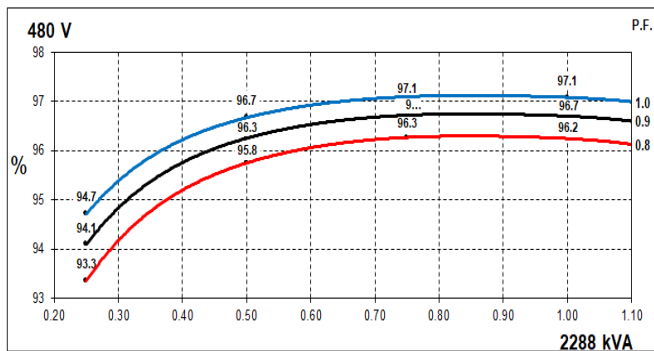
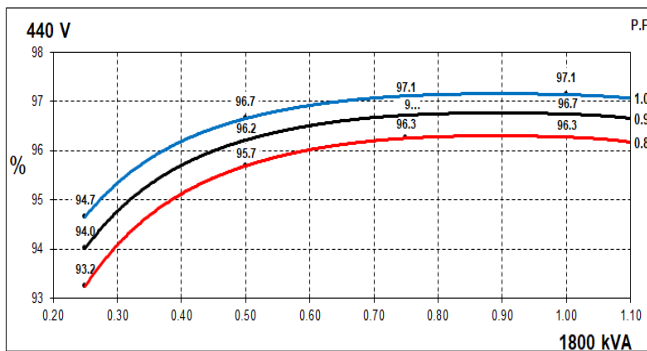
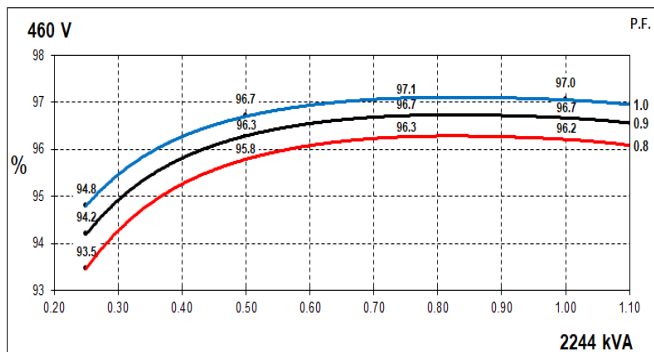
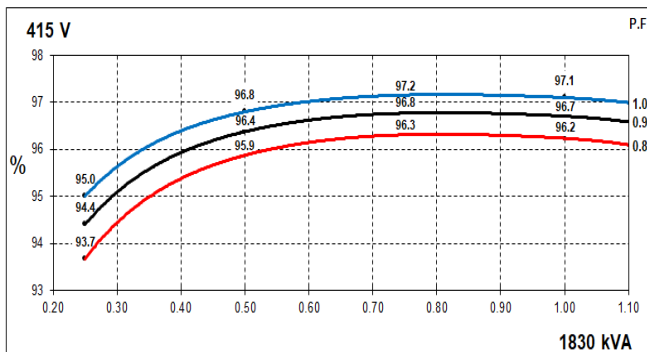
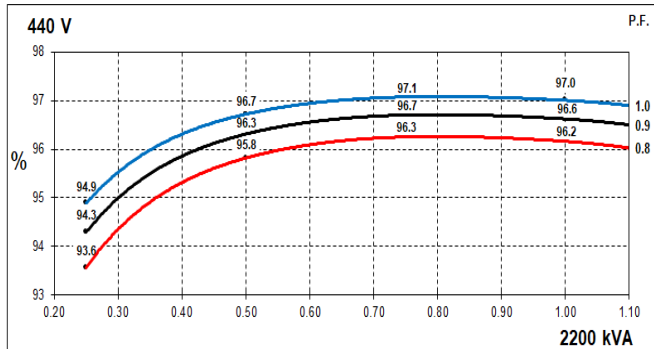
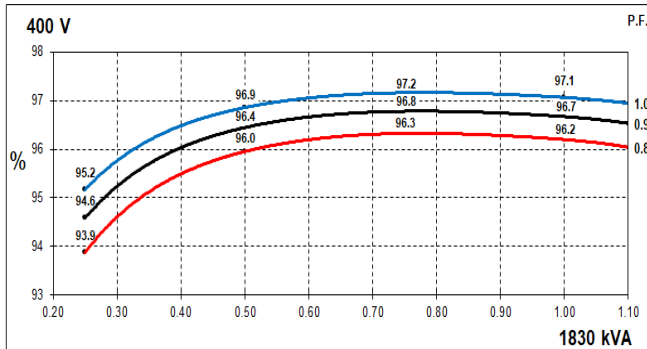
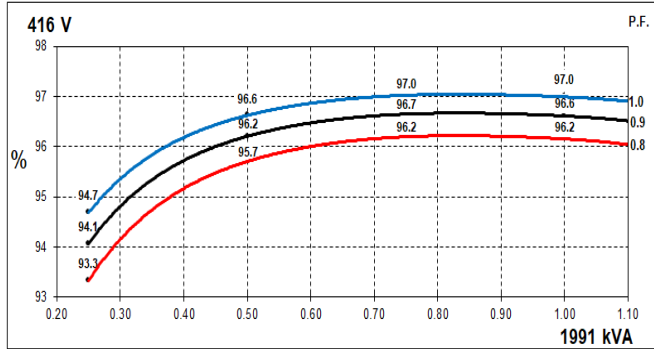
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THREE PHASE EFFICIENCY CURVES

50Hz



60Hz

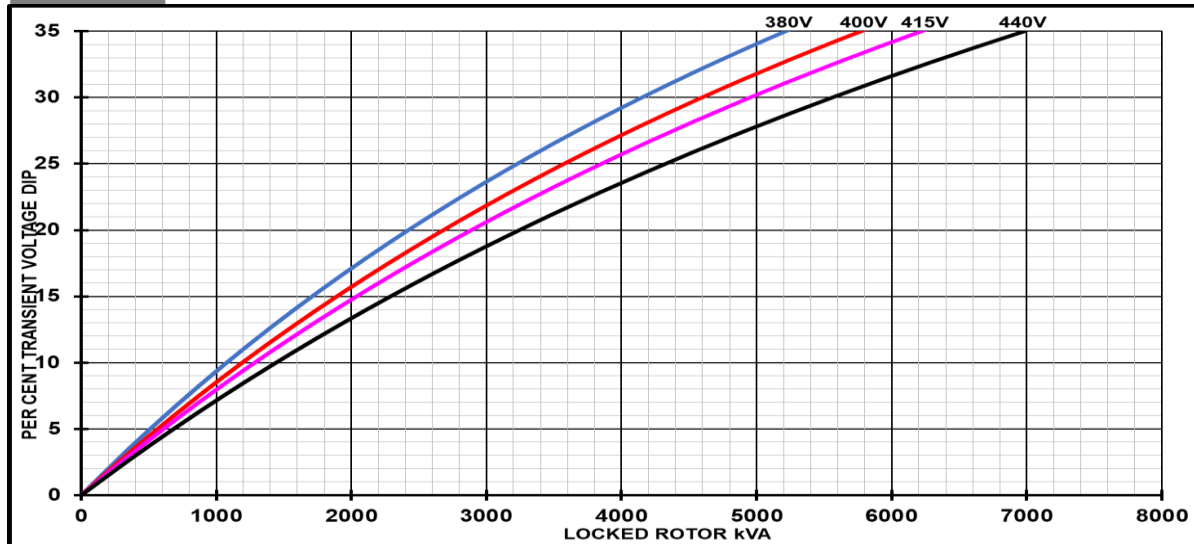


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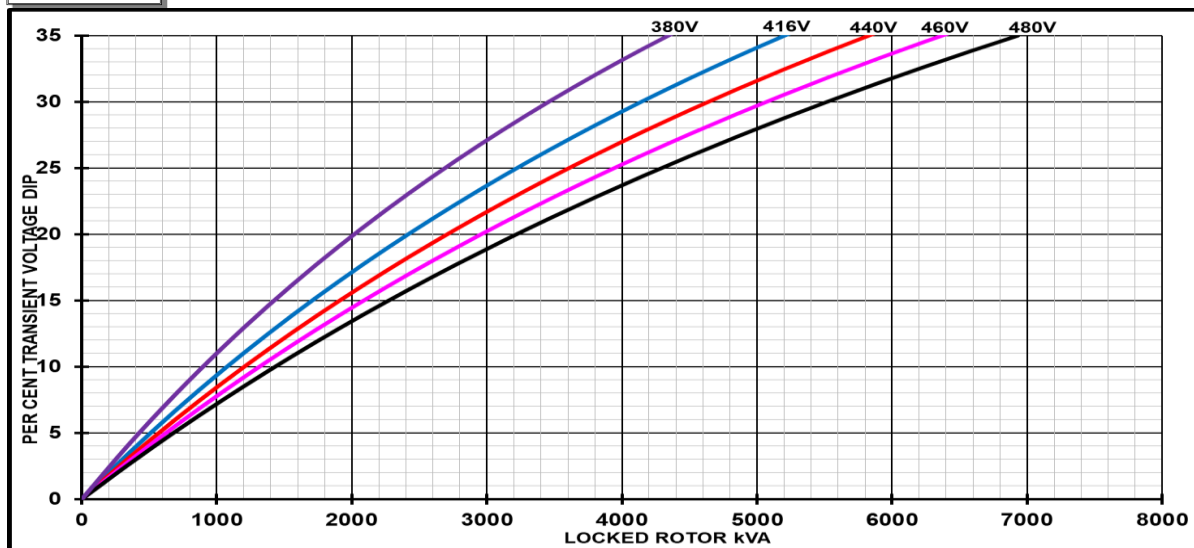
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Locked Rotor Motor Starting Curves - Separately Excited

50Hz



60Hz



Transient Voltage Dip Scaling Factor		Transient Voltage Rise Scaling Factor	
Lagging PF	Scaling Factor	Lagging PF	Scaling Factor
<= 0.4	1.00	<= 0.4	1.25
0.5	0.95	0.5	1.20
0.6	0.90	0.6	1.15
0.7	0.86	0.7	1.10
0.8	0.83	> 0.7	1.00
0.9	0.75		
0.95	0.70		
1	0.65		

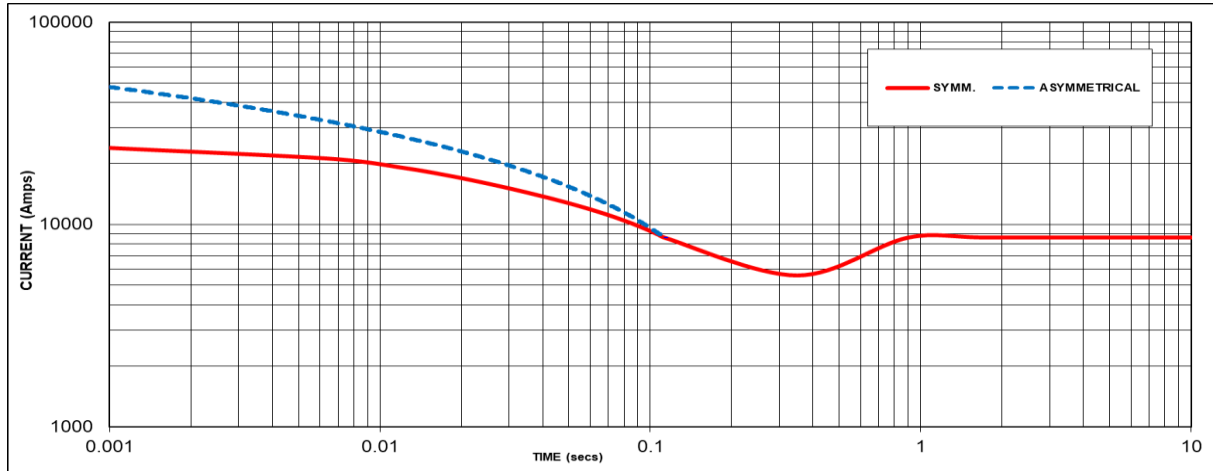
Note: To determine % Transient Voltage Dip or Voltage Rise at various PF, multiply the % Voltage Dip from the curve directly by the Scaling Factor.

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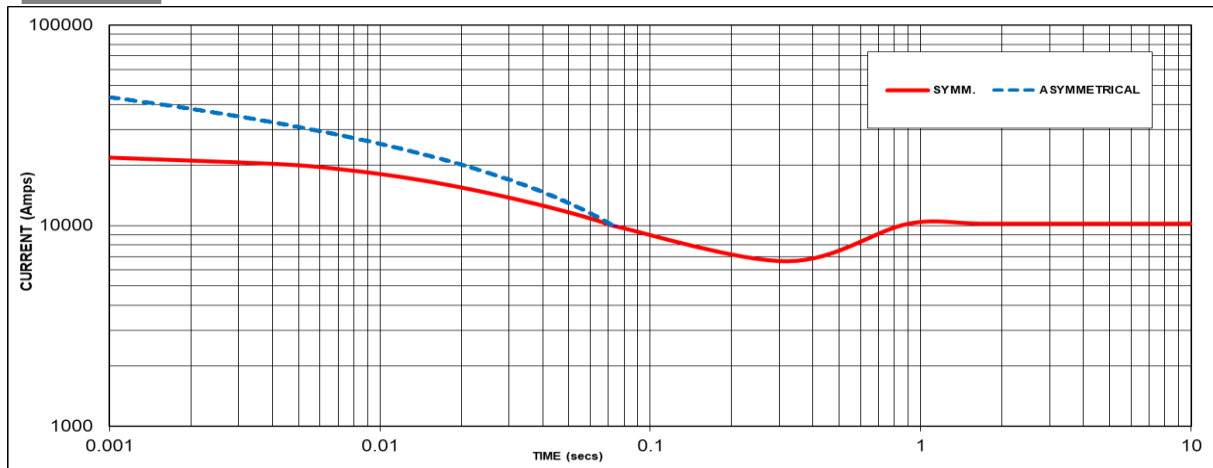
Three-phase Short Circuit Decrement Curve - Separately Excited

50Hz



Sustained Short Circuit = 8618 Amps

60Hz



Sustained Short Circuit = 10194 Amps

Note 1

The following multiplication factors should be used to adjust the values from curve between time 0.001 seconds and the minimum current point in respect of nominal operating voltage :

50Hz		60Hz	
Voltage	Factor	Voltage	Factor
380V	X 1.00	416V	X 1.00
400V	X 1.05	440V	X 1.06
415V	X 1.09	460V	X 1.10
440V	X 1.16	480V	X 1.15

The sustained current value is constant irrespective of voltage level. The alternator is capable of delivering 300% short-circuit current for 10 seconds as per requirements specified by marine agencies.

Note 2

The following multiplication factor should be used to convert the values calculated in accordance with NOTE 1 to those applicable to the various types of short circuit :

	3-phase	2-phase L-L	1-phase L-N
Instantaneous	x 1.00	x 0.87	x 1.30
Minimum	x 1.00	x 1.80	x 3.20
Sustained	x 1.00	x 1.50	x 2.50
Max. sustained duration	10 sec.	5 sec.	2 sec.

Note 3

All other times are unchanged

Curves are drawn for Star connections under no-load excitation at rated speeds. For other connection (where applicable) the following multipliers should be applied to current values as shown :

Parallel Star = Curve current value X 2

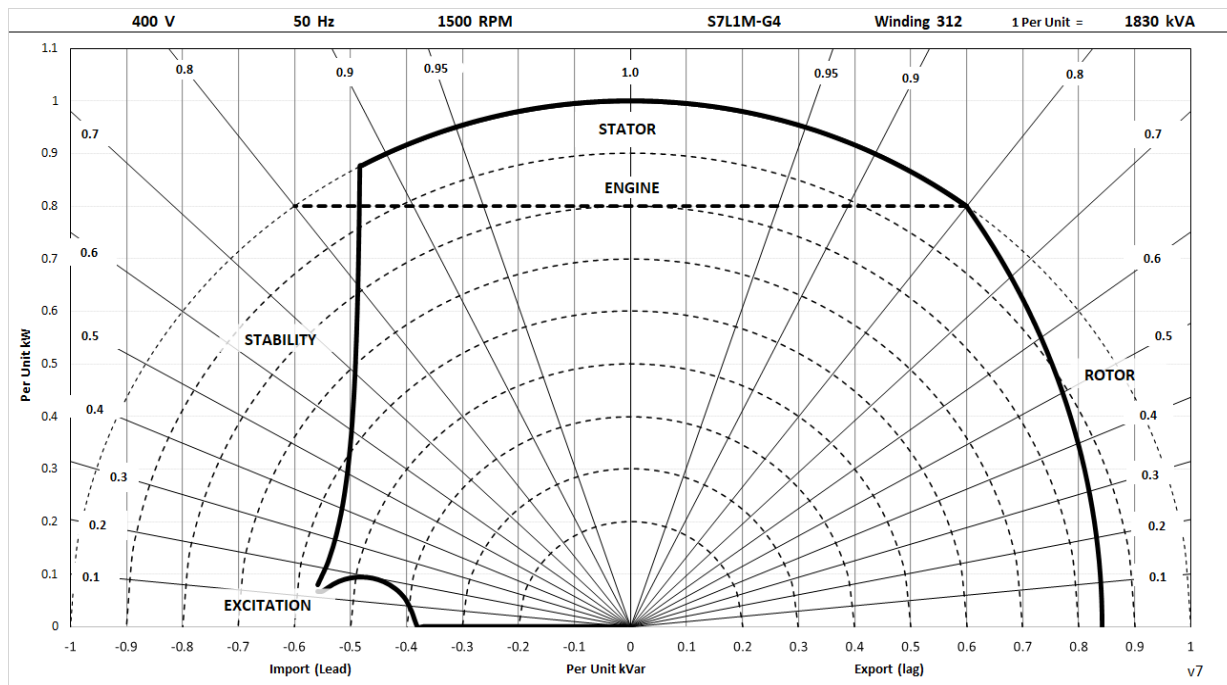
Series Delta = Curve current value X 1.732

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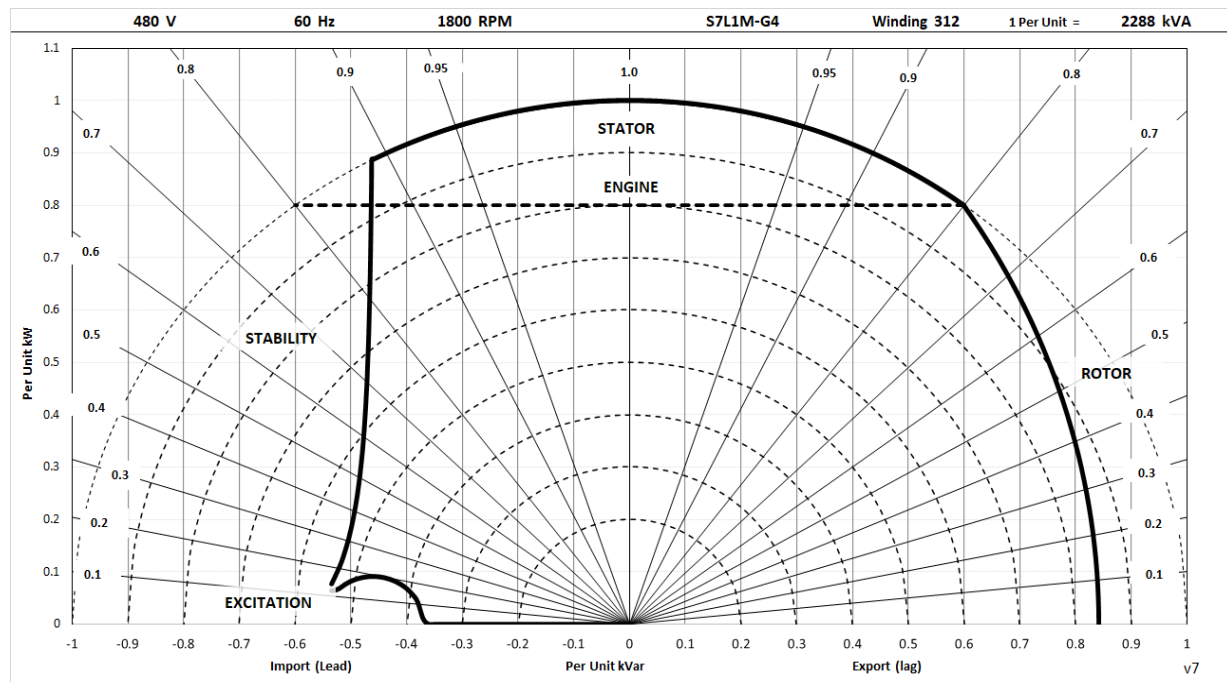
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Typical Alternator Operating Charts

400V/50Hz



480V/60Hz



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RATINGS AT 0.8 POWER FACTOR

Class - Temp Rise		Standby				Cont. H - 110/50°C				Cont. F - 90/50°C				Cont. B - 70/50°C			
50 Hz	Star (V)	380	400	415	440	380	400	415	440	380	400	415	440	380	400	415	440
	Parallel Star (V)	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A
	Delta (V)	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A
	kVA	N/A	N/A	N/A	N/A	1780	1830	1830	1800	1500	1580	1640	1665	1450	1495	1495	1465
	kW	N/A	N/A	N/A	N/A	1424	1464	1464	1440	1200	1264	1312	1332	1160	1196	1196	1172
	Efficiency (%)	N/A	N/A	N/A	N/A	96.2	96.2	96.2	96.3	96.3	96.3	96.3	96.3	96.3	96.3	96.3	96.3
	kW Input	N/A	N/A	N/A	N/A	1481	1522	1521	1496	1246	1312	1362	1383	1204	1242	1242	1217

60 Hz	Star (V)	416	440	460	480	416	440	460	480	416	440	460	480	416	440	460	480
	Parallel Star (V)	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A
	Delta (V)	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A
	kVA	N/A	N/A	N/A	N/A	1991	2200	2244	2288	1912	2037	2075	2125	1687	1800	1837	1875
	kW	N/A	N/A	N/A	N/A	1593	1760	1795	1830	1530	1630	1660	1700	1350	1440	1470	1500
	Efficiency (%)	N/A	N/A	N/A	N/A	96.2	96.2	96.2	96.2	96.2	96.2	96.3	96.3	96.2	96.3	96.3	96.3
	kW Input	N/A	N/A	N/A	N/A	1656	1830	1866	1902	1590	1694	1724	1766	1403	1496	1526	1558

De-rates

All values tabulated above are subject to the following reductions:

- 5% when air inlet filters are fitted
- 3% for every 500 meters by which the operating altitude exceeds 1000 meters above mean sea level
- 3% for every 5°C by which the operational ambient temperature exceeds 40°C @ Class H temperature rise (please refer to applications for ambient temperature de-rates at other temperature rise classes)
- For marine alternators, 3% for every 5°C by which the operational ambient temperature exceeds 50°C
- For any other operating conditions impacting the cooling circuit please refer to applications

Note: Requirement for operating in an ambient exceeding 60°C and altitude exceeding 4000 meters (for <690V) or 1500 meters (for >690V) must be referred to applications.

Dimensional and Torsional Drawing

For dimensional and torsional information please refer to the alternator General Arrangement and rotor drawings available on our website (<http://stamford-avk.com/>)

Note: Continuous development of our products means that the information contained in our data sheets can change without notice, and specifications should always be confirmed with Cummins Generator Technologies prior to purchase.



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