



S7L1D-E4 Wdg.312 - Technical Data Sheet

Standards

STAMFORD industrial alternators meet the requirements of the relevant parts of the IEC 60034 and the relevant sections of other international standards such as BS5000-3, ISO 8528-3, VDE 0530, NEMA MG1-32, CSA C22.2-100 and AS 60034. Other standards and certifications can be considered on request.

Quality Assurance

Alternators are manufactured using production procedures having a quality assurance level to BS EN ISO 9001.



*Image depicts the S7L1D alternator

Excitation and Voltage Regulators

Excitation System					
AVR Type	MX341	MX322	DECS150		
Voltage Regulation	± 1%	± 0.5%	± 0.25%		with 4% Engine Governing
AVR Power	PMG	PMG	PMG		

No Load Excitation Voltage (V)	15.4 - 14.7
No Load Excitation Current (A)	0.68 - 0.64
Full Load Excitation Voltage (V)	58
Full Load Excitation Current (A)	2.6
Exciter Time Constant (seconds)	0.125

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Electrical Data								
Insulation System	H							
Stator Winding	Double Layer Concentric							
Winding Pitch	2/3							
Winding Leads	6							
Winding Number	312							
Number of Poles	4							
IP Rating	IP23							
RFI Suppression	BS EN 61000-6-2 & BS EN 61000-6-4, VDE 0875G, VDE 0875N. Refer to factory for others							
Waveform Distortion	NO LOAD < 1.5% NON-DISTORTING BALANCED LINEAR LOAD < 5.0%							
Short Circuit Ratio	1/Xd							
Steady State X/R Ratio	25.33							
50 Hz					60 Hz			
Telephone Interference	THF<2%				TIF<50			
Cooling Air Flow	2.52 m³/sec				3.02 m³/sec			
Voltage Series (V)	380	400	415	440	416	440	460	480
Voltage Parallel Star (V)	-	-	-	-	-	-	-	-
Voltage Delta (V)	-	-	-	-	-	-	-	-
kVA Base Rating (Class H) for Reactance Values (kVA)	1700	1750	1750	1720	1837	1944	2031	2119
Saturated Values in Per Unit at Base Ratings and Voltages								
Xd Dir. Axis Synchronous	2.51	2.33	2.16	1.89	2.71	2.57	2.45	2.35
X'd Dir. Axis Transient	0.19	0.18	0.17	0.15	0.21	0.20	0.19	0.18
X''d Dir. Axis Subtransient	0.14	0.13	0.12	0.10	0.15	0.14	0.13	0.13
Xq Quad. Axis Reactance	1.86	1.73	1.61	1.41	2.01	1.91	1.82	1.75
X''q Quad. Axis Subtransient	0.22	0.20	0.19	0.16	0.23	0.22	0.21	0.20
XL Stator Leakage Reactance	0.08	0.07	0.07	0.06	0.09	0.08	0.08	0.08
X2 Negative Sequence Reactance	0.17	0.16	0.15	0.13	0.19	0.18	0.17	0.16
X0 Zero Sequence Reactance	0.03	0.03	0.03	0.02	0.03	0.03	0.03	0.03
Unsaturated Values in Per Unit at Base Ratings and Voltages								
Xd Dir. Axis Synchronous	3.01	2.80	2.60	2.27	3.26	3.08	2.94	2.82
X'd Dir. Axis Transient	0.22	0.21	0.19	0.17	0.24	0.23	0.22	0.21
X''d Dir. Axis Subtransient	0.16	0.15	0.14	0.12	0.17	0.16	0.16	0.15
Xq Quad. Axis Reactance	1.92	1.78	1.66	1.45	2.08	1.96	1.88	1.80
X''q Quad. Axis Subtransient	0.26	0.24	0.22	0.19	0.28	0.26	0.25	0.24
XL Stator Leakage Reactance	0.09	0.08	0.08	0.07	0.10	0.09	0.09	0.08
Xlr Rotor Leakage Reactance	0.20	0.18	0.17	0.15	0.21	0.20	0.19	0.19
X2 Negative Sequence Reactance	0.21	0.19	0.18	0.16	0.22	0.21	0.20	0.19
X0 Zero Sequence Reactance	0.04	0.04	0.03	0.03	0.04	0.04	0.04	0.04

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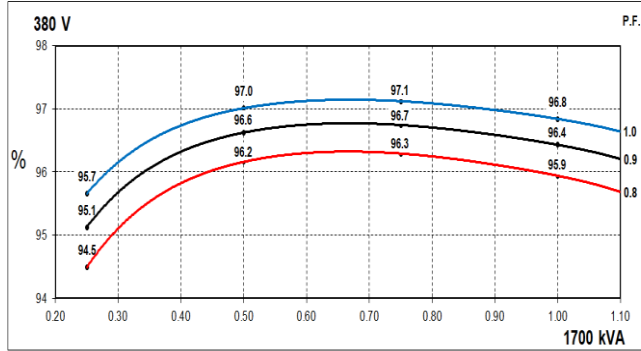
Time Constants (Seconds)		
T'd Transient Time Const.	0.150	
T''d Sub-Transient Time Const.	0.017	
T'do O.C. Field Time Const.	4.290	
Ta Armature Time Const.	0.028	
T''q Sub-Transient Time Const.	0.0100	
Resistances in Ohms (Ω) at 22° C		
Stator Winding Resistance (Ra), per phase for series connected	0.00092	
Rotor Winding Resistance (Rf)	1.95	
Exciter Stator Winding Resistance	22.3	
Exciter Rotor Winding Resistance per phase	0.065	
PMG Phase Resistance (Rpmg) per phase	1.91	
Positive Sequence Resistance (R1)	0.0012	
Negative Sequence Resistance (R2)	0.0013	
Zero Sequence Resistance (R0)	0.0012	
Saturation Factors	400V	480V
SG1.0	0.281	0.304
SG1.2	1.308	1.184
Mechanical Data		
Shaft and Keys	All alternator rotors are dynamically balanced to better than ISO 21940-11 Grade 2.5 for minimum vibration in operation. Two bearing generators are balanced with a half key.	
	1 Bearing	2 Bearing
SAE Adaptor	SAE0,00	SAE0,00
Moment of Inertia	40.98 kgm²	40.08 kgm²
Weight Wound Stator	1518kg	1518kg
Weight Wound Rotor	1353kg	1300kg
Weight Complete Alternator	3350kg	3264kg
Shipping weight in a Crate	3399kg	3313kg
Packing Crate Size	200x105x155(cm)	200x105x155(cm)
Maximum Over Speed	2250 RPM for two minutes	
Bearing Drive End	-	BALL 6228
Bearing Non-Drive End	BALL 6319	BALL 6319

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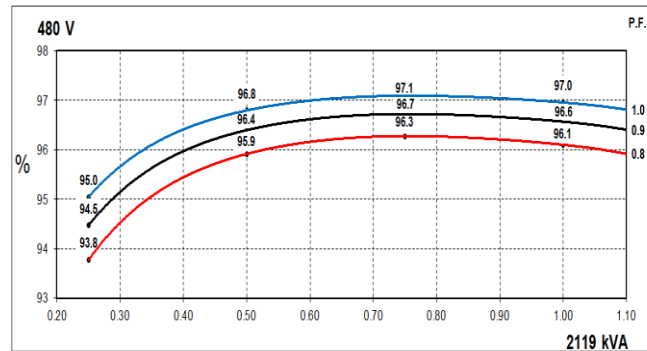
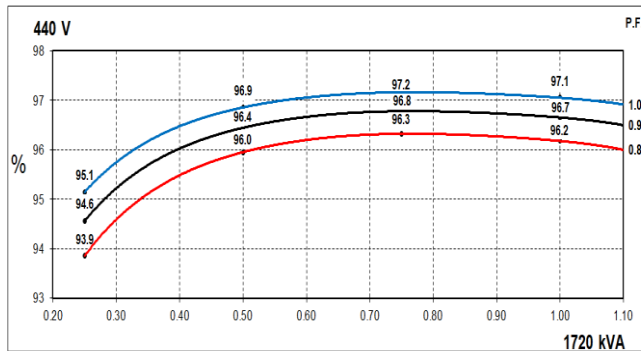
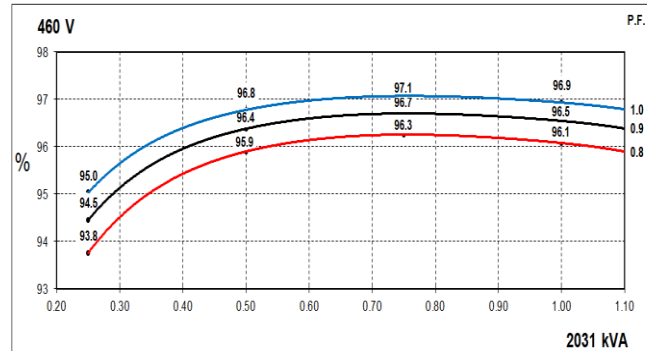
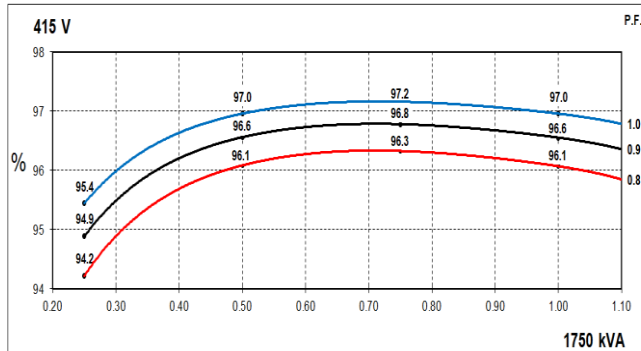
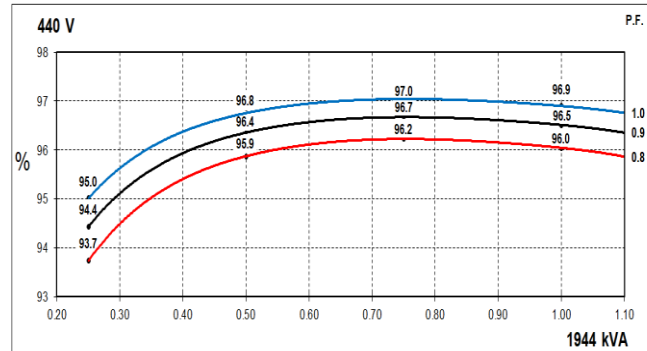
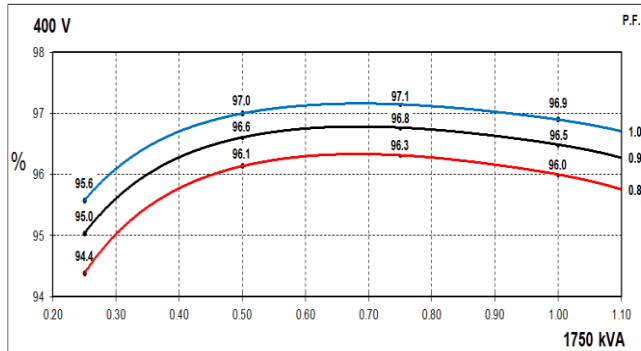
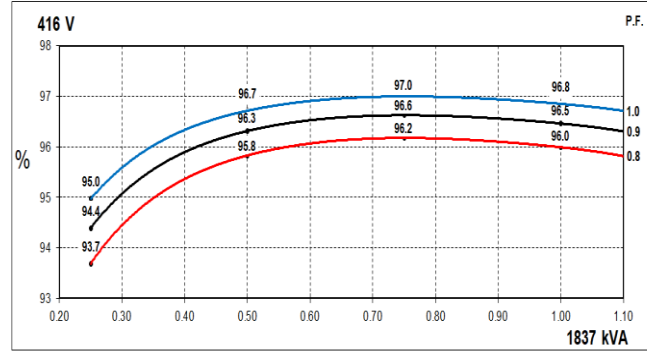
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THREE PHASE EFFICIENCY CURVES

50Hz



60Hz

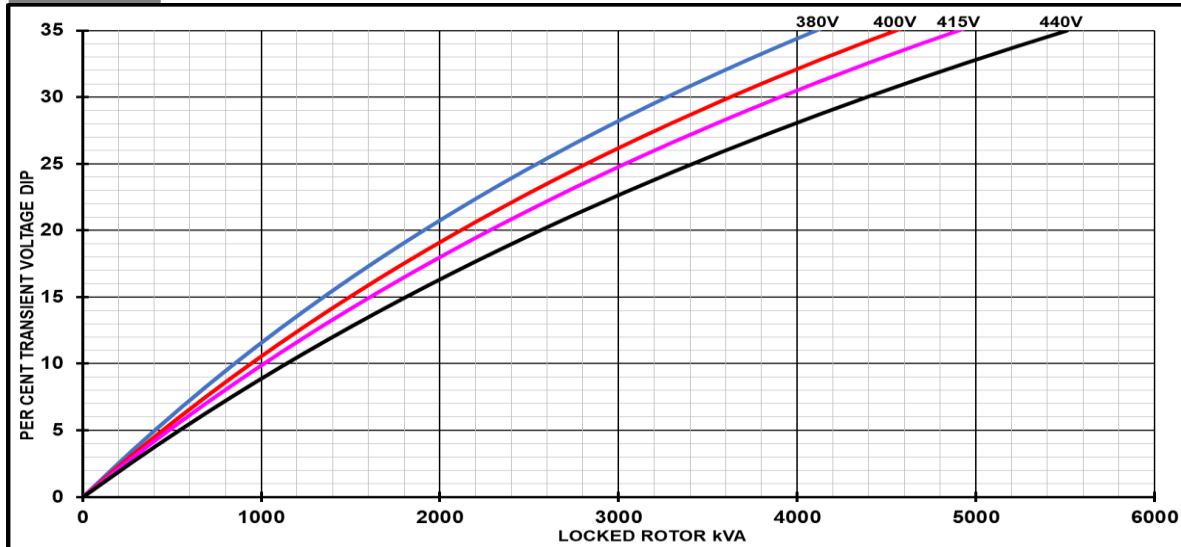


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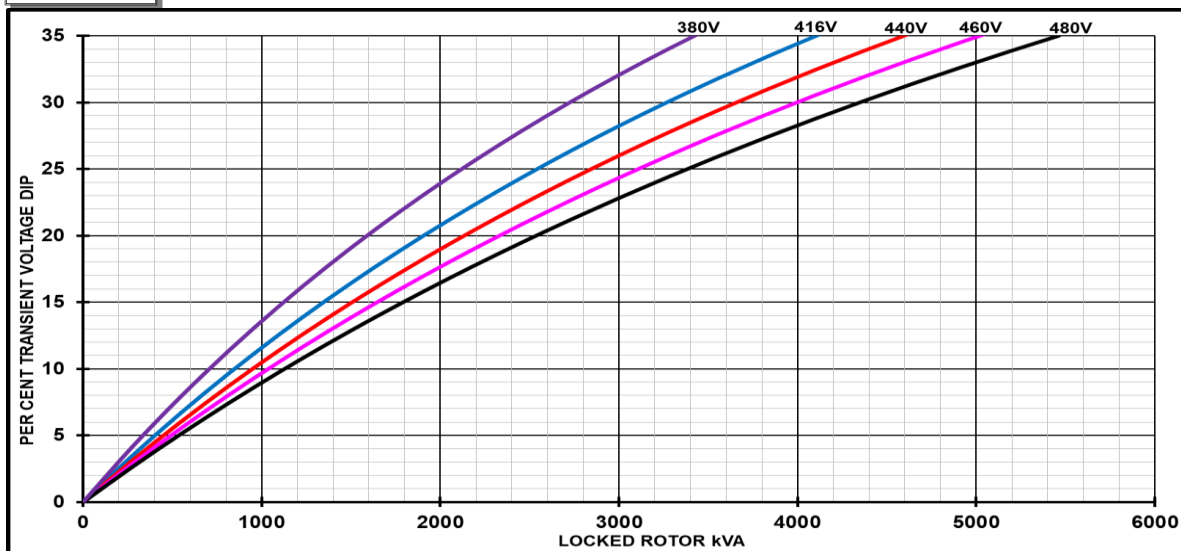
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Locked Rotor Motor Starting Curves - Separately Excited

50Hz



60Hz



Transient Voltage Dip Scaling Factor		Transient Voltage Rise Scaling Factor	
Lagging PF	Scaling Factor	Lagging PF	Scaling Factor
<= 0.4	1.00	<= 0.4	1.25
0.5	0.95	0.5	1.20
0.6	0.90	0.6	1.15
0.7	0.86	0.7	1.10
0.8	0.83	> 0.7	1.00
0.9	0.75		
0.95	0.70		
1	0.65		

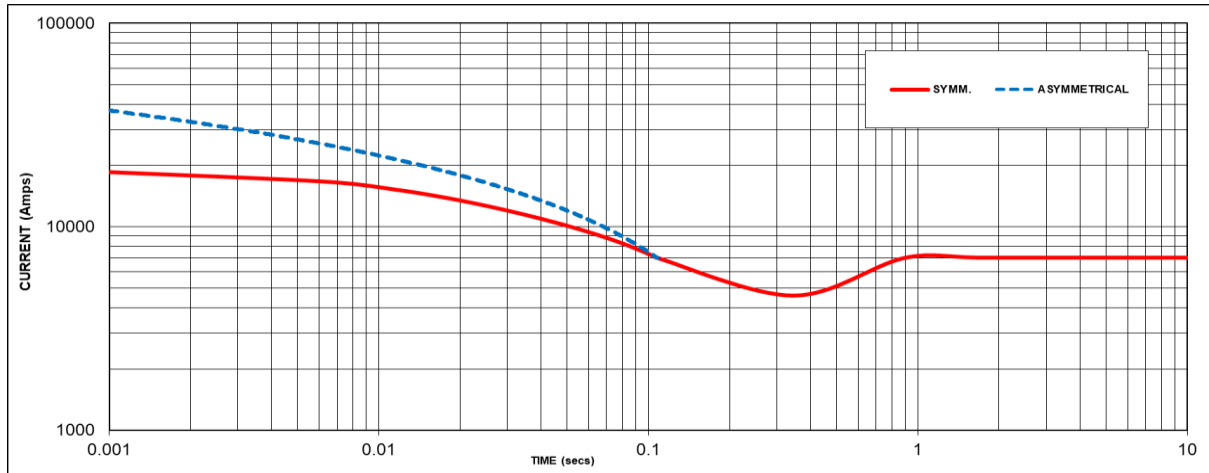
Note: To determine % Transient Voltage Dip or Voltage Rise at various PF, multiply the % Voltage Dip from the curve directly by the Scaling Factor.

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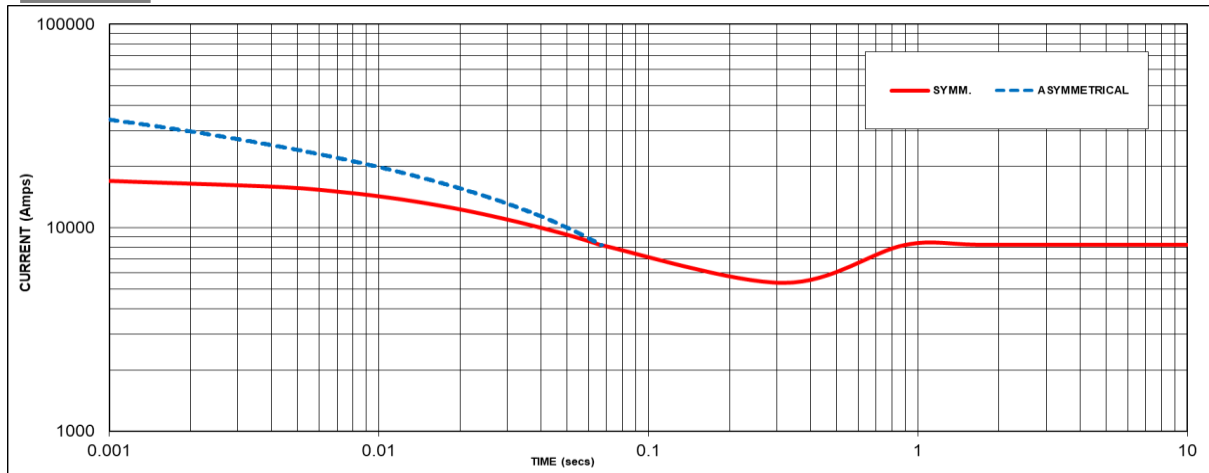
Three-phase Short Circuit Decrement Curve - Separately Excited

50Hz



60Hz

Sustained Short Circuit = 7046 Amps



Sustained Short Circuit = 8246 Amps

Note 1

The following multiplication factors should be used to adjust the values from curve between time 0.001 seconds and the minimum current point in respect of nominal operating voltage :

50Hz		60Hz	
Voltage	Factor	Voltage	Factor
380V	X 1.00	416V	X 1.00
400V	X 1.05	440V	X 1.06
415V	X 1.09	460V	X 1.1
440V	X 1.16	480V	X 1.15

The sustained current value is constant irrespective of voltage level. This alternator is capable of achieving a balanced 300% sustained short circuit for up to 10 seconds.

If MX322 or digital AVR is used, the sustained short-circuit current value is to be multiplied by a factor of 1.2.

Note 2

The following multiplication factor should be used to convert the values calculated in accordance with NOTE 1 to those applicable to the various types of short circuit :

	3-phase	2-phase L-L	1-phase L-N
Instantaneous	x 1.00	x 0.87	x 1.30
Minimum	x 1.00	x 1.80	x 3.20
Sustained	x 1.00	x 1.50	x 2.50
Max. sustained duration	10 sec.	5 sec.	2 sec.

Note 3

All other times are unchanged

Curves are drawn for Star connections under no-load excitation at rated speeds. For other connection (where applicable) the following multipliers should be applied to current values as shown :

Parallel Star = Curve current value X 2

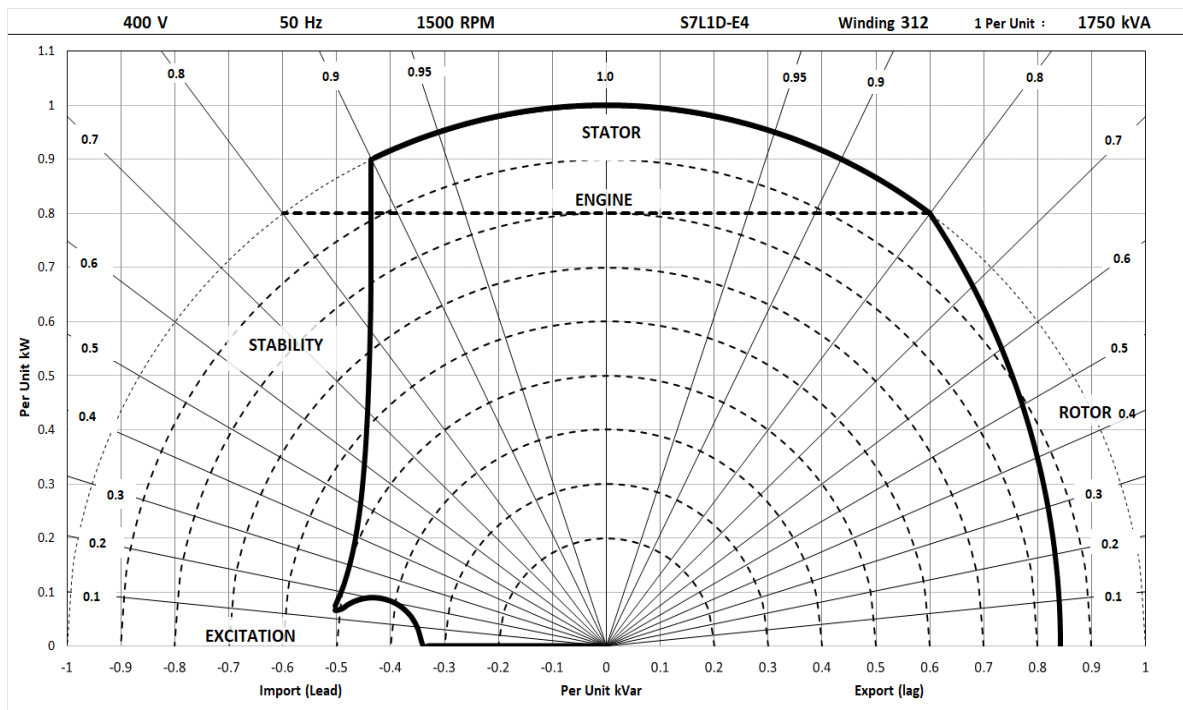
Series Delta = Curve current value X 1.732

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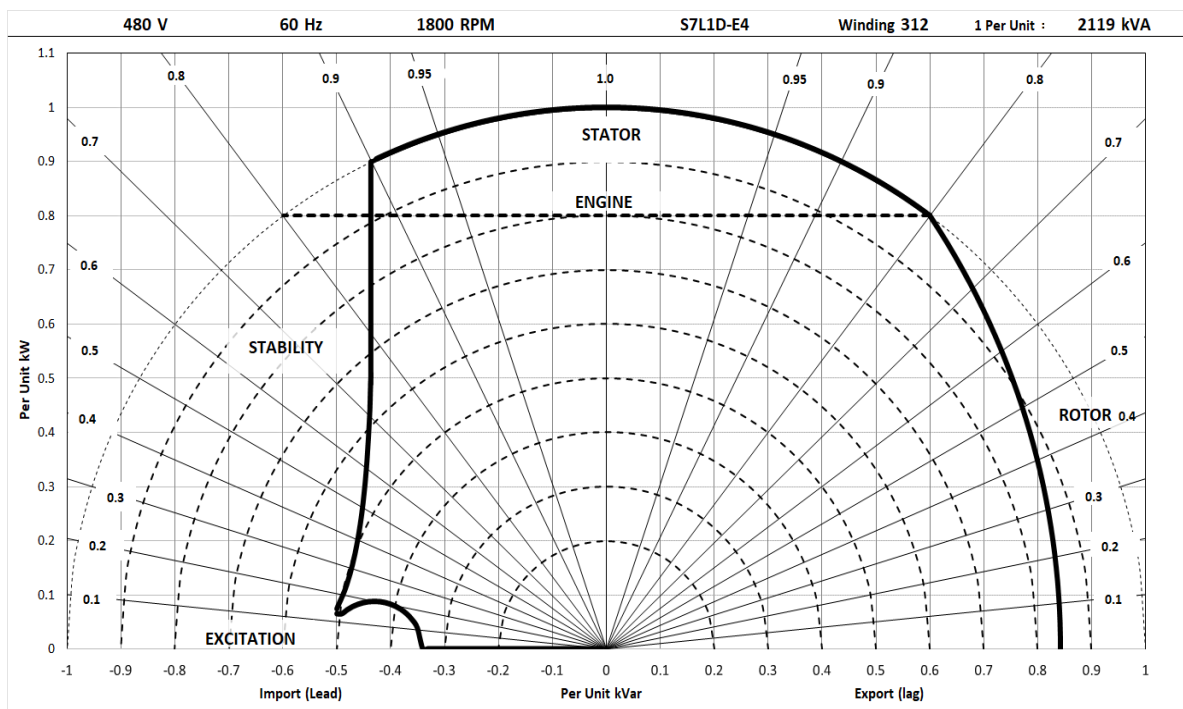
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Typical Alternator Operating Charts

400V/50Hz



480V/60Hz



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RATINGS AT 0.8 POWER FACTOR

Class - Temp Rise		Standby - 163/27°C				Standby - 150/40°C				Cont. H - 125/40°C				Cont. F - 105/40°C			
50 Hz	Star (V)	380	400	415	440	380	400	415	440	380	400	415	440	380	400	415	440
	Parallel Star (V)	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A
	Delta (V)	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A
	kVA	1819	1873	1873	1840	1768	1820	1820	1789	1700	1750	1750	1720	1580	1625	1630	1600
	kW	1455	1498	1498	1472	1414	1456	1456	1431	1360	1400	1400	1376	1264	1300	1304	1280
	Efficiency (%)	95.8	95.8	95.9	96.1	95.9	95.9	96.0	96.1	95.9	96.0	96.1	96.2	96.1	96.1	96.2	96.3
	kW Input	1519	1563	1562	1532	1476	1518	1517	1489	1418	1458	1457	1431	1316	1352	1356	1330

60 Hz	Star (V)	416	440	460	480	416	440	460	480	416	440	460	480	416	440	460	480
	Parallel Star (V)	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A
	Delta (V)	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A
	kVA	1969	2081	2175	2263	1912	2025	2112	2200	1837	1944	2031	2119	1712	1812	1888	1969
	kW	1575	1665	1740	1810	1530	1620	1690	1760	1470	1555	1625	1695	1370	1450	1510	1575
	Efficiency (%)	95.9	95.9	96.0	96.0	95.9	96.0	96.0	96.0	96.0	96.0	96.1	96.1	96.1	96.1	96.2	96.2
	kW Input	1643	1735	1813	1886	1595	1688	1760	1833	1531	1619	1691	1764	1426	1508	1571	1638

De-rates

- 5% when air inlet filters are fitted
- 3% for every 500 meters by which the operating altitude exceeds 1000 meters above mean sea level
- 3% for every 5°C by which the operational ambient temperature exceeds 40°C @ Class H temperature rise
- For marine alternators (IP23), 3% for every 5°C by which the operational ambient temperature exceeds 50°C
- For any other operating conditions impacting the cooling circuit please refer to applications

Note: Requirement for operating in an ambient exceeding 60°C and altitude exceeding 4000 meters (for <690V) or 1500 meters (for >690V) must be referred to applications.

Dimensional and Torsional Drawing

For dimensional and torsional information please refer to the alternator General Arrangement and rotor drawings available on our website (<http://stamford-avk.com/>)

Note: Continuous development of our products means that the information contained in our data sheets can change without notice, and specifications should always be confirmed with Cummins Generator Technologies prior to purchase.



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