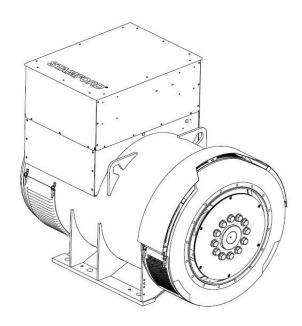
# S7L1M-F4 & S7L1W-F4 (Marine) Wdg.26 - Technical Data Sheet

## **Standards**

STAMFORD industrial alternators meet the requirements of the relevant parts of the IEC 60034 and the relevant sections of other international standards such as BS5000-3, ISO 8528-3, VDE 0530, NEMA MG1-32, CSA C22.2-100 and AS 60034. Other standards and certifications can be considered on request.

## **Quality Assurance**

Alternators are manufactured using production procedures having a quality assurance level to BS EN ISO 9001.



<sup>\*</sup>Image depicts the S7L1M alternator

### **Excitation and Voltage Regulators**

Excitation System						
AVR Type	MX322	DECS100	DECS150			
Voltage Regulation	± 0.5%	± 0.25%	± 0.25%		with 4% Engine Governing	
AVR Power	PMG	PMG	PMG			

No Load Excitation Voltage (V)	19.3
No Load Excitation Current (A)	0.87
Full Load Excitation Voltage (V)	64
Full Load Excitation Current (A)	2.8
Exciter Time Constant (seconds)	0.125

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Electrical Data		
Insulation System	I	+
Stator Winding	Double Laye	er Concentric
Winding Pitch	2	/3
Winding Leads		6
Winding Number	2	26
Number of Poles		4
IP Rating	IP23 or IP44*	(see footnote)
RFI Suppression		00-6-4,VDE 0875G, VDE 0875N. ory for others
Waveform Distortion	NO LOAD < 1.5% NON-DISTORTIN	G BALANCED LINEAR LOAD < 5.0%
Short Circuit Ratio	1/	Xd
Steady State X/R Ratio	24	.08
	50	Hz
Telephone Interference	THF	i<2%
Cooling Air Flow	2.52 ו	m³/sec
Voltage Star (V)	660	690
Voltage Parallel Star (V)	-	-
Voltage Delta (V)	-	-
kVA Base Rating (Class H) for Reactance Values (kVA)	1579	1640
Saturated Values in Per Unit	at Base Ratings and Voltages	
Xd Dir. Axis Synchronous	2.58	2.45
X'd Dir. Axis Transient	0.20	0.19
X"d Dir. Axis Subtransient	0.14	0.13
Xq Quad. Axis Reactance	1.85	1.76
X"q Quad. Axis Subtransient	0.22	0.21
XL Stator Leakage Reactance	0.08	0.07
X2 Negative Sequence Reactance	0.17	0.16
X0 Zero Sequence Reactance	0.02	0.02
Unsaturated Values in Per Ur	nit at Base Ratings and Voltages	
Xd Dir. Axis Synchronous	3.09	2.94
X'd Dir. Axis Transient	0.23	0.22
X"d Dir. Axis Subtransient	0.16	0.15
Xq Quad. Axis Reactance	1.90	1.81
X"q Quad. Axis Subtransient	0.26	0.25
XL Stator Leakage Reactance	0.09	0.08
XIr Rotor Leakage Reactance	0.20	0.19
X2 Negative Sequence Reactance	0.21	0.20
X0 Zero Sequence Reactance	0.03	0.03

### \*Notes:

<sup>1)</sup> S7L1W: IP44 rating with IC81W cooling (watercooled) and 38°C water inlet temperature.

<sup>2)</sup> S7L1M: IP23 rating with IC01 cooling (open-circuit cooling) as standard.

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Time Constants (Seconds)						
T'd Transient Time Const.	0.1	155				
T"d Sub-Transient Time Const.	0.018					
T'do O.C. Field Time Const.						
Ta Armature Time Const.	4.050 0.036					
T"q Sub-Transient Time Const.		094				
Resistances in Ohms (Ω) at 2						
Stator Winding Resistance (Ra),						
per phase for series connected	0.00	0262				
Rotor Winding Resistance (Rf)	1.	95				
Exciter Stator Winding Resistance	22	2.3				
Exciter Rotor Winding Resistance per	0.0	065				
phase						
PMG Phase Resistance (Rpmg) per phase	1.	91				
Positive Sequence Resistance (R1)	0.0	033				
Negative Sequence Resistance (R2)	0.0	038				
Zero Sequence Resistance (R0)	0.0033					
Saturation Factors	690V					
SG1.0	0.22					
SG1.2	1.781					
Mechanical Data						
Shaft and Keys		ed to better than ISO 21940-11 Grade 2.5 for ng generators are balanced with a half key.				
	1 Bearing	2 Bearing				
SAE Adaptor	SAE 0, 00	SAE 0, 00				
Moment of Inertia	40.98 kgm²	40.08 kgm²				
Weight Wound Stator	1518kg	1518kg				
Weight Wound Rotor	1353kg 1300kg					
Weight Complete Alternator	3350kg	3264kg				
Shipping weight in a Crate	3399kg	3313kg				
Packing Crate Size	200 x 105 x 155(cm)	200 x 105 x 155(cm)				
Maximum Over Speed	2250 RPM for two minutes					
Bearing Drive End	- BALL. 6228; Sleeve EFWLK 14 (optional)					
Bearing Non-Drive End	BALL. 6319 BALL. 6319; Sleeve EFNLQ 11 (optional					
Notes:						

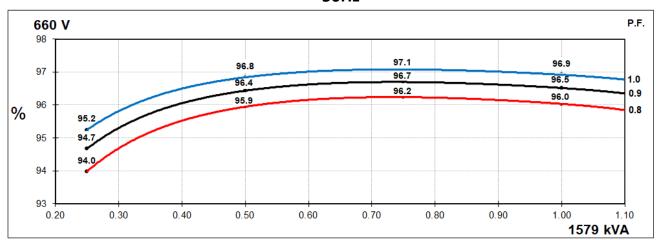
#### Notes:

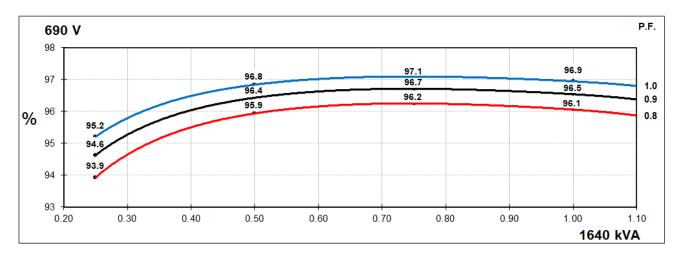
- 1) Mechanical data are applicable for S7L1M with anti-friction bearing. Refer the GA and rotor drawings for S7L1W and sleeve bearing.
- 2) S7L1W and/ or sleeve bearings are available for 2-bearing alternators only.
- 3) SAE adaptor options are not applicable for sleeve bearing.



## THREE PHASE EFFICIENCY CURVES

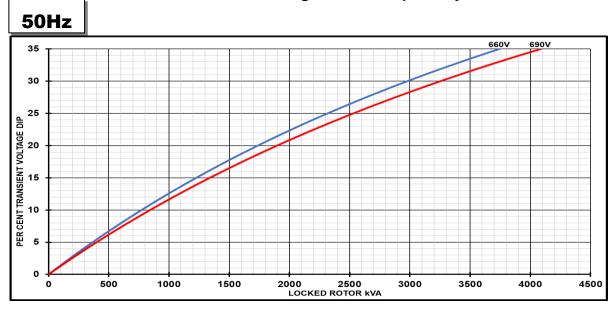
## 50Hz





# S7L1M-F4 & S7L1W-F4 (Marine) Wdg.26

**Locked Rotor Motor Starting Curves - Separately Excited** 



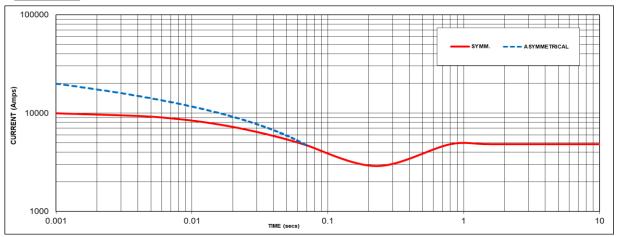
Transient Voltage	Dip Scaling Factor	Transient Voltage I	Rise Scaling Factor
Lagging PF	Lagging PF Scaling Factor		Scaling Factor
<= 0.4	1.00	<= 0.4	1.25
0.5	0.95	0.5	1.20
0.6	0.6 0.90		1.15
0.7	0.86	0.7	1.10
0.8	0.83	> 0.7	1.00
0.9	0.75		_
0.95	0.70		
1	0.65		

Note: To determine % Transient Voltage Dip or Voltage Rise at various PF, multiply the % Voltage Dip from the curve directly by the Scaling Factor.

# S7L1M-F4 & S7L1W-F4 (Marine) Wdg.26

### Three-phase Short Circuit Decrement Curve - Separately Excited





Sustained Short Circuit = 4831 Amps

#### Note 1

The following multiplication factors should be used to adjust the values from curve between time 0.001 seconds and the minimum current point in respect of nominal operating voltage:

50	Hz	60Hz		
Voltage	Factor	Voltage	Factor	
660V	X 1.00	-	-	
690V	X 1.05	-	-	
-	-	-	-	
-	-	-	-	

The sustained current value is constant irrespective of voltage level

#### Note 2

The following multiplication factor should be used to convert the values calculated in accordance with NOTE 1 to those applicable to the various types of short circuit:

	3-phase	2-phase L-L	1-phase L-N
Instantaneous	x 1.00	x 0.87	x 1.30
Minimum	x 1.00	x 1.80	x 3.20
Sustained	x 1.00	x 1.50	x 2.50
Max. sustained duration	10 sec.	5 sec.	2 sec.

Note 3 All other times are unchanged

Curves are drawn for Star connections under no-load excitation at rated speeds. For other connection (where applicable) the following multipliers should be applied to current values as shown:

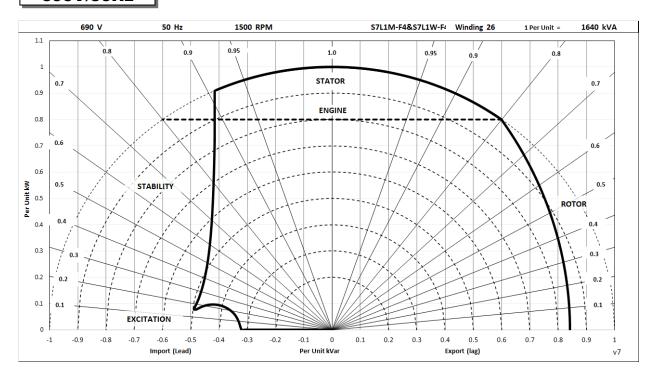
Parallel Star = Curve current value X 2 Series Delta = Curve current value X 1.732



# S7L1M-F4 & S7L1W-F4 (Marine) Wdg.26

# **Typical Alternator Operating Charts**

## 690V/50Hz



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## S7L1M-F4 & S7L1W-F4 (Marine) Wdg.26

#### **RATINGS AT 0.8 POWER FACTOR**

	Class - Temp Rise	Star	ndby	Cont. H -	110/50°C	Cont. F -	90/50°C	Cont. B -	· 70/50°C
	Star (V)	660	690	660	690	660	690	660	690
50	Parallel Star (V)	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A
Hz	Delta (V)	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A
	kVA	N/A	N/A	1579	1640	1440	1440	1275	1275
	kW	N/A	N/A	1263	1312	1152	1152	1020	1020
	Efficiency (%)	N/A	N/A	96.0	96.1	96.1	96.2	96.2	96.3
	kW Input	N/A	N/A	1315	1366	1198	1198	1060	1060

	Star (V)	N/A	N/A	N/A	N/A
60	Parallel Star (V)	N/A	N/A	N/A	N/A
Hz	Delta (V)	N/A	N/A	N/A	N/A
	kVA	N/A	N/A	N/A	N/A
	kW	N/A	N/A	N/A	N/A
	Efficiency (%)	N/A	N/A	N/A	N/A
	kW Input	N/A	N/A	N/A	N/A

#### Note:

For S7L1W marine application, ratings are applicable for water inlet temperature up to maximum 38°C.

### De-rates

All values tabulated above are subject to the following reductions:

- 5% when air inlet filters are fitted
- 3% for every 500 meters by which the operating altitude exceeds 1000 meters above mean sea level
- 3% for every 5°C by which the operational ambient temperature exceeds 40°C @ Class H temperature rise (not applicable to S7L1W)
- For marine alternators (IP23), 3% for every 5°C by which the operational ambient temperature exceeds 50°C
- For any other operating conditions impacting the cooling circuit please refer to applications

Note: Requirement for operating in an ambient exceeding 60°C and altitude exceeding 4000 meters (for <690V) or 1500 meters (for >690V) must be referred to applications.

### **Dimensional and Torsional Drawing**

For dimensional and torsional information please refer to the alternator General Arrangement and rotor drawings available on our website (http://stamford-avk.com/)

**Note:** Continuous development of our products means that the information contained in our data sheets can change without notice, and specifications should always be confirmed with Cummins Generator Technologies prior to purchase.



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For Applications Support: applications@cummins.com

For Customer Service: emea.service@cummins.com

For General Enquiries: Stamford-avk@cummins.com

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