STAMFORD

S9H1D-A4 Wdg.63 - Technical Data Sheet

Standards

STAMFORD industrial alternators meet the requirements of the relevant parts of the IEC 60034 and the relevant sections of other international standards such as BS5000-3, ISO 8528-3, VDE 0530, NEMA MG1-32, CSA C22.2-100 and AS 60034. Other standards and certifications can be considered on request.

Quality Assurance

Alternators are manufactured using production procedures having a quality assurance level to BS EN ISO 9001.



Excitation and Voltage Regulators

Excitation System						
AVR Type	DM110	DECS100	DECS150			
Voltage Regulation	± 0.25%	± 0.25%	± 0.25%		with 4% Engine Governing	
AVR Power	PMG	PMG	PMG			

No Load Excitation Voltage (V)	10.8 - 11.1
No Load Excitation Current (A)	0.99 - 0.89
Full Load Excitation Voltage (V)	40.8
Full Load Excitation Current (A)	3.47
Exciter Time Constant (seconds)	0.34

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Electrical Data				
Insulation System	Н			
Stator Winding	Double Layer Lap			
Winding Pitch	5/6			
Winding Leads		6		
Winding Number	(53		
Number of Poles		4		
IP Rating	IP	223		
RFI Suppression		00-6-4,VDE 0875G, VDE 0875N. ory for others		
Waveform Distortion	NO LOAD < 1.5% NON-DISTORTIN	G BALANCED LINEAR LOAD < 5.0%		
Short Circuit Ratio	1/	/Xd		
Steady State X/R Ratio	26	3.18		
	50 Hz	60 Hz		
Telephone Interference	THF<2%	TIF<50		
Cooling Air Flow	2.78 m³/sec	3.33 m³/sec		
Voltage Series Star (V)	5500	6600		
Voltage Parallel Star (V)	-	-		
Voltage Delta (V)	-	-		
kVA Base Rating (Class H) for Reactance Values (kVA)	1900	2400		
Saturated Values in Per Unit	at Base Ratings and Voltages			
Xd Dir. Axis Synchronous	2.323	2.445		
X'd Dir. Axis Transient	0.281	0.296		
X"d Dir. Axis Subtransient	0.184	0.193		
Xq Quad. Axis Reactance	1.096	1.154		
X"q Quad. Axis Subtransient	0.296	0.312		
XL Stator Leakage Reactance	0.170	0.179		
X2 Negative Sequence Reactance	0.275	0.289		
X0 Zero Sequence Reactance	0.132	0.139		
Unsaturated Values in Per Ur	nit at Base Ratings and Voltages			
Xd Dir. Axis Synchronous	2.788	2.934		
X'd Dir. Axis Transient	0.323	0.340		
X"d Dir. Axis Subtransient	0.215	0.226		
Xq Quad. Axis Reactance	1.129	1.188		
X"q Quad. Axis Subtransient	0.355	0.374		
XL Stator Leakage Reactance	0.192	0.202		
XIr Rotor Leakage Reactance	0.234	0.246		
X2 Negative Sequence Reactance	0.330	0.347		
X0 Zero Sequence Reactance	0.154	0.163		



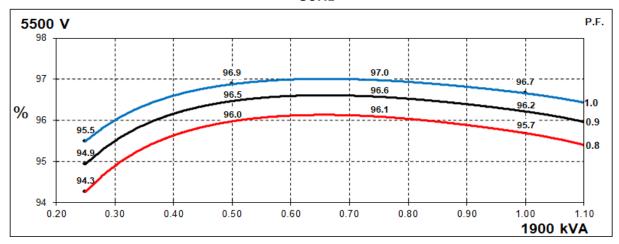
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Time Constants (Seconds)			
T'd Transient Time Const.	0.2	267	
T''d Sub-Transient Time Const.	0.0	021	
T'do O.C. Field Time Const.	2.340		
Ta Armature Time Const.	0.039		
T''q Sub-Transient Time Const.	0.0260		
Resistances in Ohms (Ω) at 2	22°C		
Stator Winding Resistance (Ra),		680	
per phase for series connected	0.1		
Rotor Winding Resistance (Rf)	0.	48	
Exciter Stator Winding Resistance	9	.8	
Exciter Rotor Winding Resistance per phase	0.0	014	
PMG Phase Resistance (Rpmg) per phase	3	8	
Positive Sequence Resistance (R1)	0.2	100	
Negative Sequence Resistance (R2)	0.2	419	
Zero Sequence Resistance (R0)	0.2	100	
Saturation Factors	5500V	6600V	
SG1.0	0.182	0.182	
SG1.2	0.886	0.888	
SG1.2 Mechanical Data	0.886	0.888	
		petter than ISO 21940-11 Grade 2.5 for minimum	
Mechanical Data	All alternator rotors are dynamically balanced to	petter than ISO 21940-11 Grade 2.5 for minimum	
Mechanical Data	All alternator rotors are dynamically balanced to vibration in operation. Two bearing ge	petter than ISO 21940-11 Grade 2.5 for minimum inerators are balanced with a half key.	
Mechanical Data Shaft and Keys	All alternator rotors are dynamically balanced to vibration in operation. Two bearing ge	petter than ISO 21940-11 Grade 2.5 for minimum nerators are balanced with a half key. 2 Bearing	
Mechanical Data Shaft and Keys SAE Adaptor	All alternator rotors are dynamically balanced to vibration in operation. Two bearing generating 1 Bearing 0, 00	petter than ISO 21940-11 Grade 2.5 for minimum perators are balanced with a half key. 2 Bearing 0, 00, None	
Mechanical Data Shaft and Keys SAE Adaptor Moment of Inertia	All alternator rotors are dynamically balanced to l vibration in operation. Two bearing ge 1 Bearing 0, 00 65.8 kgm²	petter than ISO 21940-11 Grade 2.5 for minimum nerators are balanced with a half key. 2 Bearing 0, 00, None 63.7 kgm²	
Mechanical Data Shaft and Keys SAE Adaptor Moment of Inertia Weight Wound Stator	All alternator rotors are dynamically balanced to vibration in operation. Two bearing get a Bearing 0, 00 65.8 kgm² 1500kg	petter than ISO 21940-11 Grade 2.5 for minimum nerators are balanced with a half key. 2 Bearing 0, 00, None 63.7 kgm² 1500kg	
Mechanical Data Shaft and Keys SAE Adaptor Moment of Inertia Weight Wound Stator Weight Wound Rotor	All alternator rotors are dynamically balanced to vibration in operation. Two bearing get a Bearing 0, 00 65.8 kgm² 1500kg 1686kg	petter than ISO 21940-11 Grade 2.5 for minimum nerators are balanced with a half key. 2 Bearing 0, 00, None 63.7 kgm² 1500kg 1614kg	
Mechanical Data Shaft and Keys SAE Adaptor Moment of Inertia Weight Wound Stator Weight Wound Rotor Weight Complete Alternator	All alternator rotors are dynamically balanced to vibration in operation. Two bearing get 1 Bearing 0, 00 65.8 kgm² 1500kg 1686kg 4800kg	petter than ISO 21940-11 Grade 2.5 for minimum inerators are balanced with a half key. 2 Bearing 0, 00, None 63.7 kgm² 1500kg 1614kg 4800kg	
Mechanical Data Shaft and Keys SAE Adaptor Moment of Inertia Weight Wound Stator Weight Wound Rotor Weight Complete Alternator Shipping weight in a Crate	All alternator rotors are dynamically balanced to vibration in operation. Two bearing get a Bearing 0, 00 65.8 kgm² 1500kg 1686kg 4800kg 5150kg 160 x 200 x 220(cm)	petter than ISO 21940-11 Grade 2.5 for minimum nerators are balanced with a half key. 2 Bearing 0, 00, None 63.7 kgm² 1500kg 1614kg 4800kg 5150kg	
Mechanical Data Shaft and Keys SAE Adaptor Moment of Inertia Weight Wound Stator Weight Wound Rotor Weight Complete Alternator Shipping weight in a Crate Packing Crate Size	All alternator rotors are dynamically balanced to vibration in operation. Two bearing get a Bearing 0, 00 65.8 kgm² 1500kg 1686kg 4800kg 5150kg 160 x 200 x 220(cm)	petter than ISO 21940-11 Grade 2.5 for minimum nerators are balanced with a half key. 2 Bearing 0, 00, None 63.7 kgm² 1500kg 1614kg 4800kg 5150kg 160 x 200 x 220(cm)	

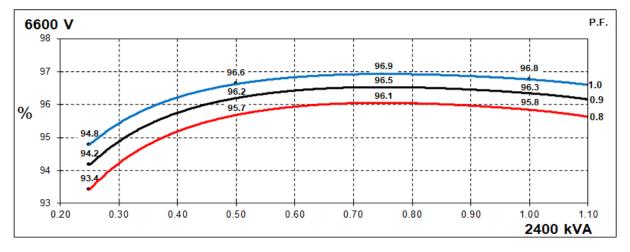


THREE PHASE EFFICIENCY CURVES

50Hz

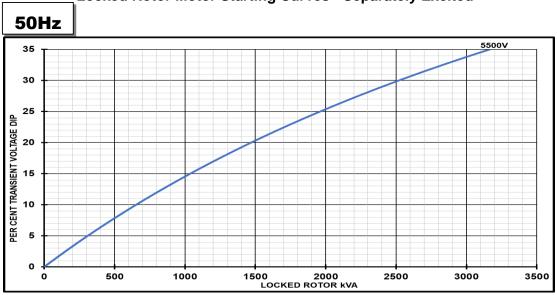


60Hz





Locked Rotor Motor Starting Curves - Separately Excited



60Hz 6600V 35 30 25 PER CENT TRANSIENT VOLTAGE DIP 20 15 10 5 0 -2000 2500 LOCKED ROTOR KVA 1000 1500 3000 3500 4000

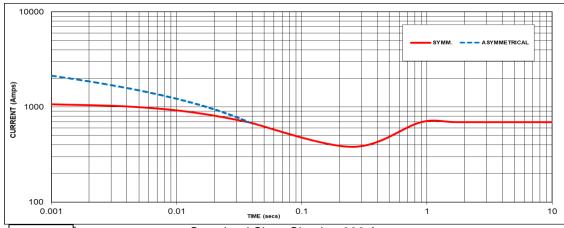
	Transient Voltage	Dip Scaling Factor	Transient Voltage Rise Scaling Factor		
	Lagging PF	Scaling Factor	Lagging PF	Scaling Factor	
	<= 0.4	1.00	<= 0.4	1.25	
	0.5	0.95	0.5	1.20	
	0.6	0.90	0.6	1.15	
	0.7	0.86	0.7	1.10	
	0.8	0.83	> 0.7	1.00	
	0.9	0.75			
	0.95	0.70			
1		0.65			

Note: To determine % Transient Voltage Dip or Voltage Rise at various PF, multiply the % Voltage Dip from the curve directly by the Scaling Factor.



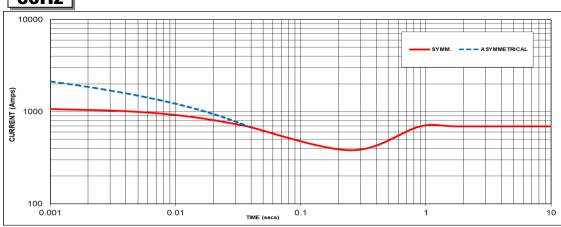
Three-phase Short Circuit Decrement Curve - Separately Excited

50Hz



60Hz

Sustained Short Circuit = 660 Amps



Sustained Short Circuit = 693 Amps

Note 1

The following multiplication factors should be used to adjust the values from curve between time 0.001 seconds and the minimum current point in respect of nominal operating voltage:

50	Hz	60Hz		
Voltage	Factor	Voltage	Factor	
5500V	X 1.00	6600V	X 1.00	
-			-	
		-	-	
		-	-	

The sustained current value is constant irrespective of voltage level

Note 2

The following multiplication factor should be used to convert the values calculated in accordance with NOTE 1 to those applicable to the various types of short circuit:

	3-phase	2-phase L-L	1-phase L-N
Instantaneous	x 1.00	x 0.87	x 1.30
Minimum	x 1.00	x 1.80	x 3.20
Sustained	x 1.00	x 1.50	x 2.50
Max. sustained duration	10 sec.	5 sec.	2 sec.

Note 3

All other times are unchanged

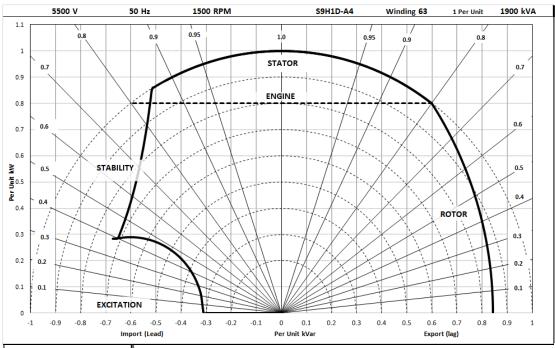
Curves are drawn for Star connections under no-load excitation at rated speeds. For other connection (where applicable) the following multipliers should be applied to current values as shown:

Parallel Star = Curve current value X 2 Series Delta = Curve current value X 1.732

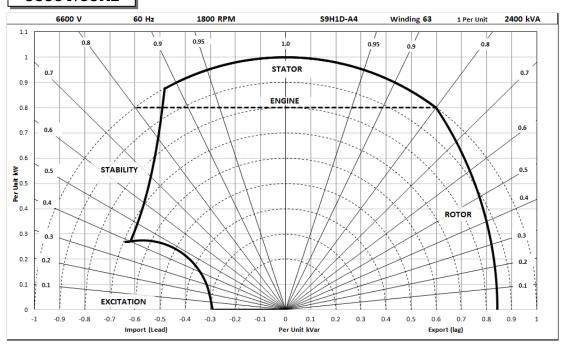


Typical Alternator Operating Charts

5500V/50Hz



6600V/60Hz





RATINGS AT 0.8 POWER FACTOR

	Class - Temp Rise	Standby - 163/27°C	Standby - 150/40°C	Cont. H - 125/40°C	Cont. F - 105/40°C
	Star (V)	5500	5500	5500	5500
50	Parallel Star (V)	N/A	N/A	N/A	N/A
Hz	Delta (V)	N/A	N/A	N/A	N/A
	kVA	2090	2033	1900	1748
	kW	1672	1626	1520	1398
	Efficiency (%)	95.4	95.5	95.7	95.9
	kW Input	1752	1703	1588	1459
-					
	Star (V)	6600	6600	6600	6600
60	Parallel Star (V)	N/A	N/A	N/A	N/A
Hz	Delta (V)	N/A	N/A	N/A	N/A
	kVA	2640	2568	2400	2208
	kW	2112	2054	1920	1766
	Efficiency (%)	95.6	95.7	95.8	96.0
	kW Input	2208	2146	2003	1841

De-rates

All values tabulated above are subject to the following reductions:

- 5% when air inlet filters are fitted
- 3% for every 500 meters by which the operating altitude exceeds 1000 meters above mean sea level
- 3% for every 5°C by which the operational ambient temperature exceeds 40°C @ Class H temperature rise (please refer to applications for ambient temperature de-rates at other temperature rise classes)
- For any other operating conditions impacting the cooling circuit please refer to applications

Note: Requirement for operating in an ambient exceeding 60°C and altitude exceeding 4000 meters (for <690V) or 1500 meters (for >690V) must be referred to applications.

Dimensional and Torsional Drawing

For dimensional and torsional information please refer to the alternator General Arrangement and rotor drawings available on our website (http://stamford-avk.com/)

Note: Continuous development of our products means that the information contained in our data sheets can change without notice, and specifications should always be confirmed with Cummins Generator Technologies prior to purchase.







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