

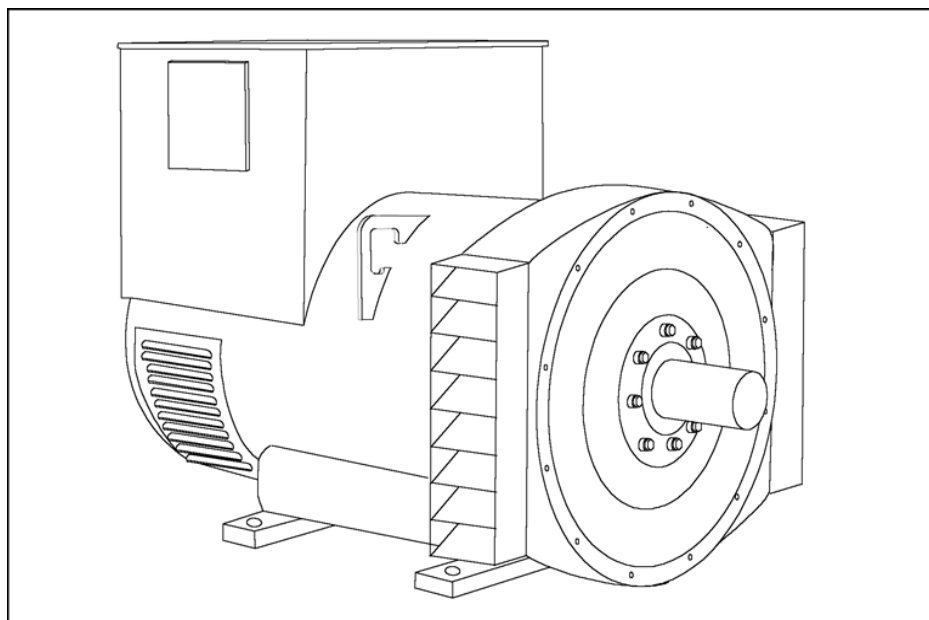
S4L1M-C4 Wdg.311 - Technical Data Sheet

Standards

STAMFORD industrial alternators meet the requirements of the relevant parts of the IEC EN 60034 and the relevant section of other international standards such as BS5000, VDE 0530, NEMA MG1-32, IEC34, CSA C22.2-100 and AS1359. Other standards and certifications can be considered on request.

Quality Assurance

Alternators are manufactured using production procedures having a quality assurance level to BS EN ISO 9001.



Excitation and Voltage Regulators

Excitation System					
AVR Type	AS440	MX341	MX321		
Voltage Regulation	± 1%	± 1%	± 0.5%		with 4% Engine Governing
AVR Power	Self-Excited	PMG	PMG		

No Load Excitation Voltage (V)	12 - 9
No Load Excitation Current (A)	0.7 - 0.5
Full Load Excitation Voltage (V)	43-40
Full Load Excitation Current (A)	2.4-2.2
Exciter Time Constant (seconds)	0.105

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Electrical Data								
Insulation System	Class H							
Stator Winding	Double Layer Lap							
Winding Pitch	Two Thirds							
Winding Leads	12							
Winding Number	311							
Number of Poles	4							
IP Rating	IP23							
RFI Suppression	BS EN 61000-6-2 & BS EN 61000-6-4, VDE 0875G, VDE 0875N. Refer to factory for others							
Waveform Distortion	NO LOAD < 1.5% NON-DISTORTING BALANCED LINEAR LOAD < 5.0%							
Short Circuit Ratio	1/Xd							
Steady State X/R Ratio	11.86							
	50 Hz				60 Hz			
Telephone Interference	THF<2%				TIF<50			
Cooling Air	0.8 m ³ /sec				0.99 m ³ /sec			
Voltage Star	380	400	415	440	416	440	460	480
kVA Base Rating (Class H) for Reactance Values	215	215	215	215	255	260	265	270
Saturated Values in Per Unit at Base Ratings and Voltages								
Xd Dir. Axis Synchronous	2.71	2.44	2.27	2.02	3.34	3.05	2.84	2.66
X'd Dir. Axis Transient	0.17	0.15	0.14	0.13	0.22	0.20	0.18	0.17
X''d Dir. Axis Subtransient	0.12	0.11	0.10	0.09	0.14	0.13	0.12	0.11
Xq Quad. Axis Reactance	2.33	2.10	1.95	1.73	2.88	2.62	2.45	2.29
X''q Quad. Axis Subtransient	0.34	0.31	0.29	0.26	0.39	0.35	0.33	0.31
XL Stator Leakage Reactance	0.09	0.08	0.07	0.06	0.09	0.08	0.07	0.07
X2 Negative Sequence Reactance	0.24	0.22	0.20	0.18	0.27	0.25	0.23	0.21
X0 Zero Sequence Reactance	0.09	0.08	0.07	0.06	0.09	0.08	0.07	0.07
Unsaturated Values in Per Unit at Base Ratings and Voltages								
Xd Dir. Axis Synchronous	3.25	2.93	2.72	2.42	4.01	3.65	3.41	3.19
X'd Dir. Axis Transient	0.20	0.18	0.17	0.15	0.25	0.23	0.21	0.20
X''d Dir. Axis Subtransient	0.14	0.13	0.12	0.11	0.16	0.15	0.14	0.13
Xq Quad. Axis Reactance	2.39	2.16	2.01	1.79	2.96	2.70	2.52	2.36
X''q Quad. Axis Subtransient	0.41	0.37	0.35	0.31	0.47	0.42	0.40	0.37
XL Stator Leakage Reactance	0.10	0.09	0.08	0.07	0.10	0.09	0.08	0.08
Xlr Rotor Leakage Reactance	0.11	0.10	0.10	0.08	0.13	0.12	0.11	0.11
X2 Negative Sequence Reactance	0.29	0.26	0.24	0.21	0.32	0.29	0.27	0.26
X0 Zero Sequence Reactance	0.10	0.09	0.08	0.07	0.10	0.09	0.09	0.08

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Time Constants (Seconds)		
T'd TRANSIENT TIME CONST.	0.08	
T''d SUB-TRANSTIME CONST.	0.019	
T'do O.C. FIELD TIME CONST.	1.7	
Ta ARMATURE TIME CONST.	0.018	
T''q SUB-TRANSTIME CONST.	0.0304	
Resistances in Ohms (Ω) at 22^oC		
Stator Winding Resistance (Ra), per phase for series connected	0.0166	
Rotor Winding Resistance (Rf)	0.92	
Exciter Stator Winding Resistance	18	
Exciter Rotor Winding Resistance per phase	0.068	
PMG Phase Resistance (Rpmg) per phase	1.9	
Positive Sequence Resistance (R1)	0.02075	
Negative Sequence Resistance (R2)	0.023904	
Zero Sequence Resistance (R0)	0.02075	
Saturation Factors	400V	480V
SG1.0	0.29	0.29
SG1.2	1.13	1.13
Mechanical Data		
Shaft and Keys	All alternator rotors are dynamically balanced to better than BS6861: Part 1 Grade 2.5 for minimum vibration in operation. Two bearing generators are balanced with a half key.	
	1 Bearing	2 Bearings
SAE Adaptor	SAE 0, 0.5, 1, 2, 3	SAE 0, 0.5, 1, 2
Moment of Inertia	3.5531 kgm ²	3.3543 kgm ²
Weight Wound Stator	370 kg	370 kg
Weight Wound Rotor	324 kg	301 kg
Weight Complete Alternator	850 kg	885 kg
Shipping weight in a Crate	920 kg	945 kg
Packing Crate Size	155 x 87 x 107 (cm)	155 x 87 x 107 (cm)
Maximum Over Speed	2250 RPM for two minutes	
Bearing Drive End	N/A	Ball 6317
Bearing Non-Drive End	Ball 6314	Ball 6314

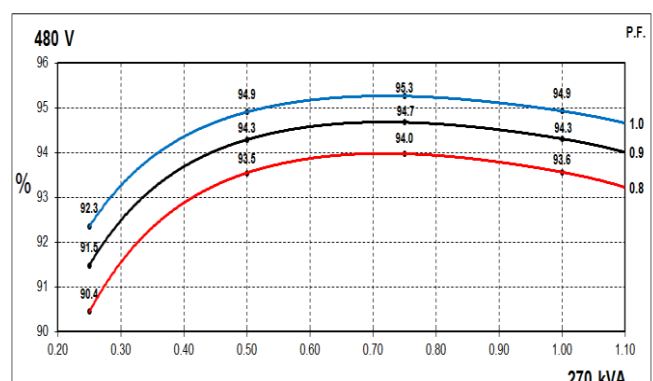
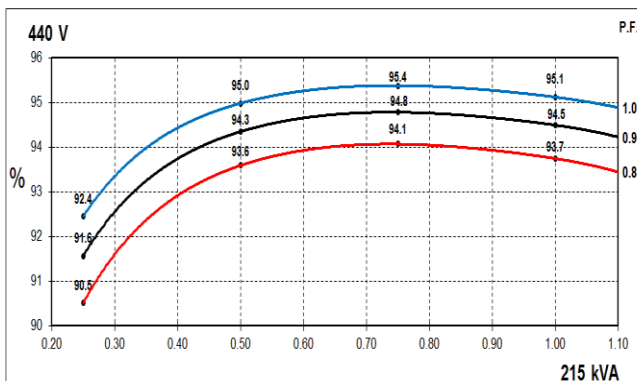
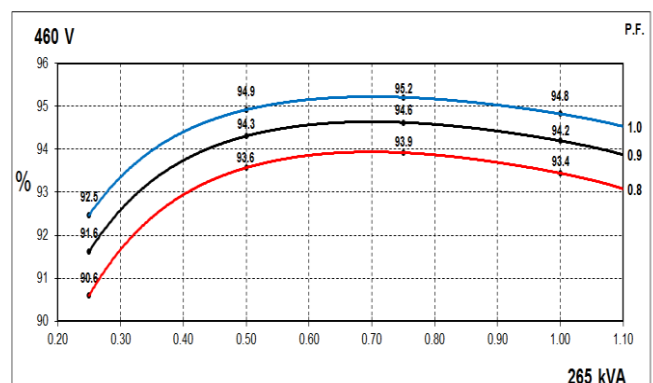
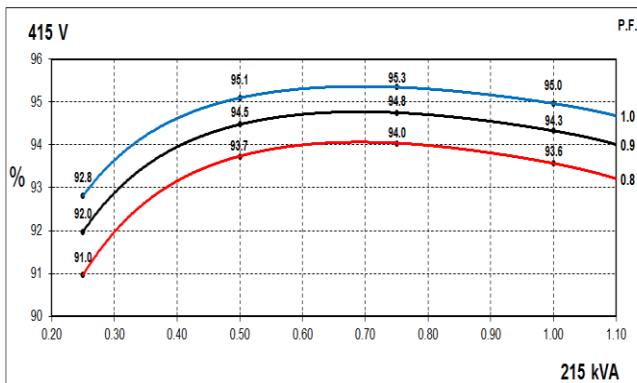
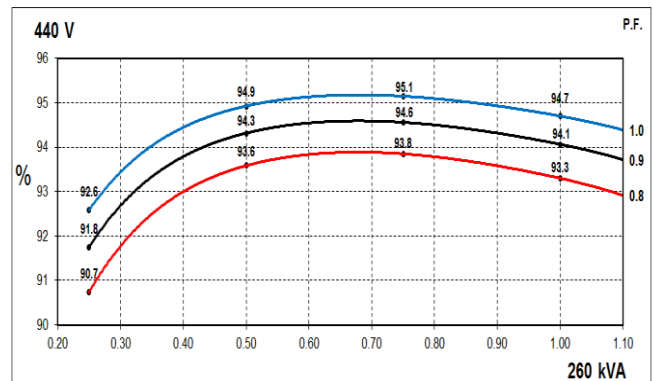
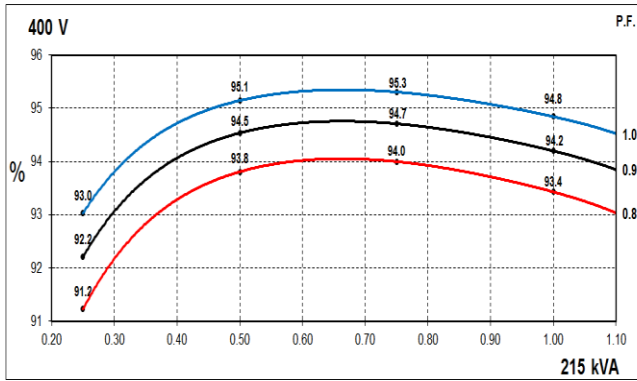
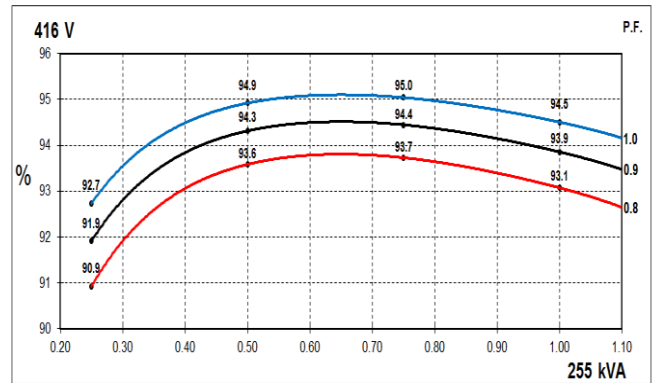
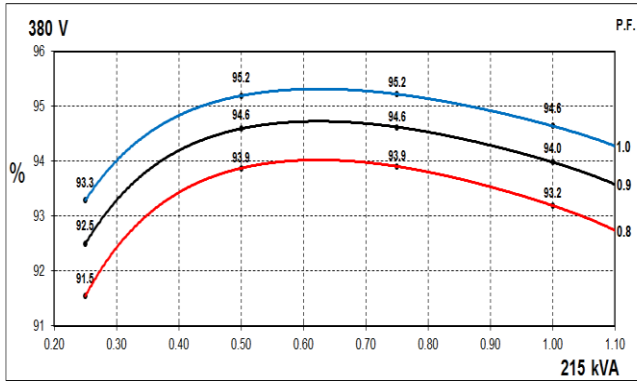
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THREE PHASE EFFICIENCY CURVES

50Hz

60Hz

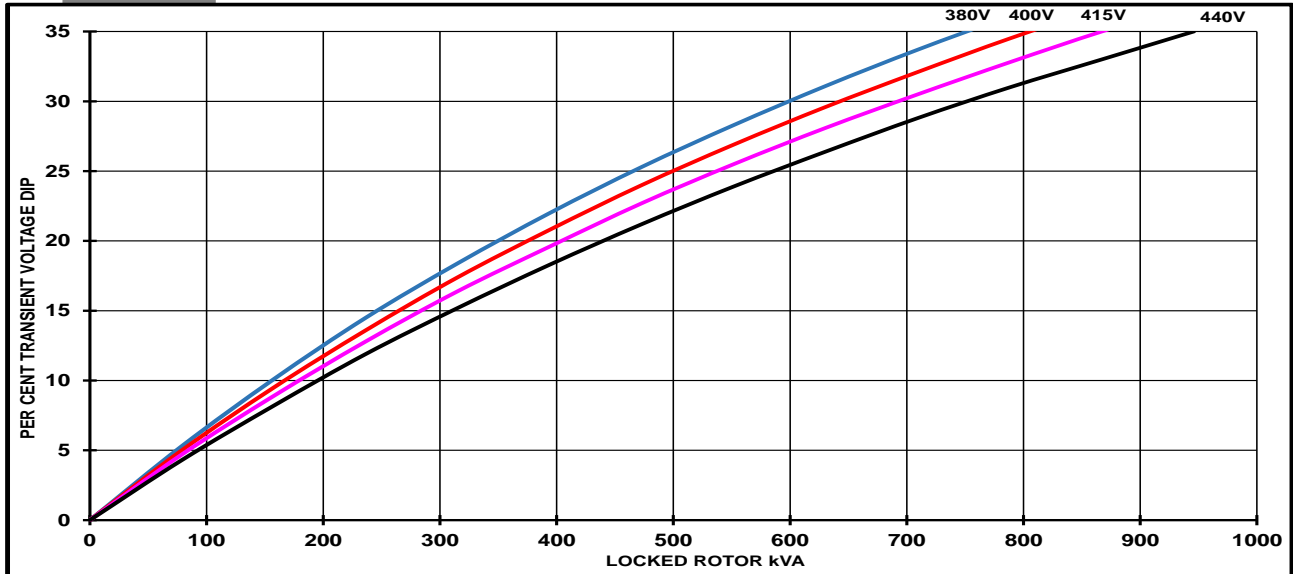


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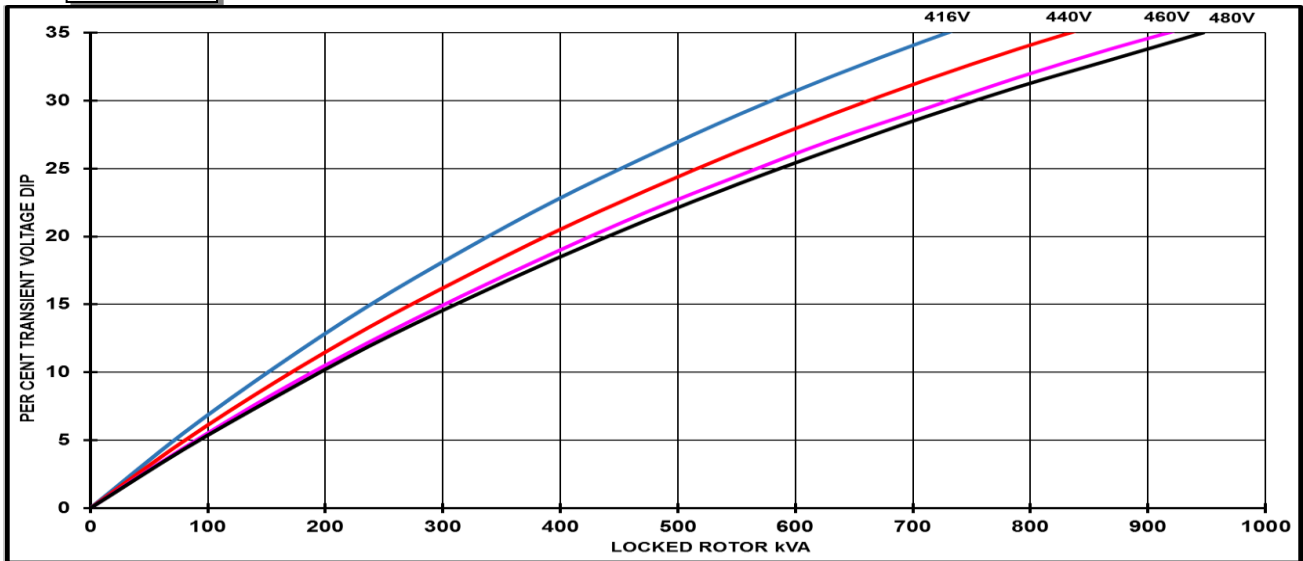
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Locked Rotor Motor Starting Curves - Separately Excited

50Hz



60Hz



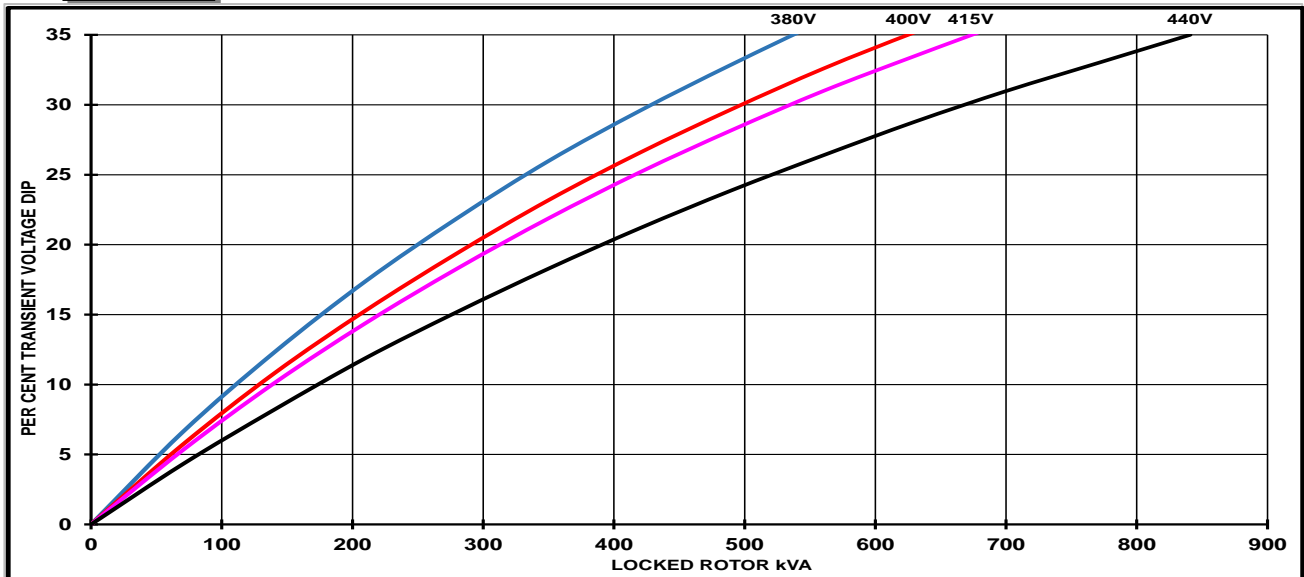
Transient Voltage Dip Scaling Factor		Transient Voltage Rise Scaling Factor
PF	Factor	
< 0.5	1	For voltage rise multiply voltage dip by 1.25
0.5	0.97	
0.6	0.93	
0.7	0.9	
0.8	0.85	
0.9	0.83	

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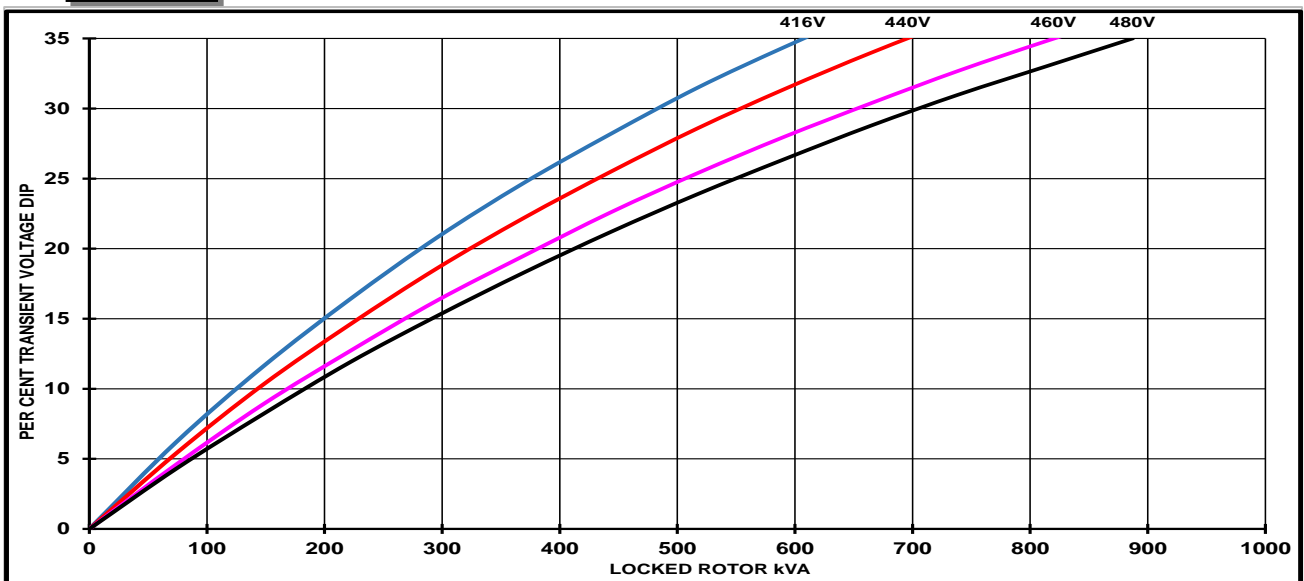
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Locked Rotor Motor Starting Curves - Self Excited

50Hz



60Hz



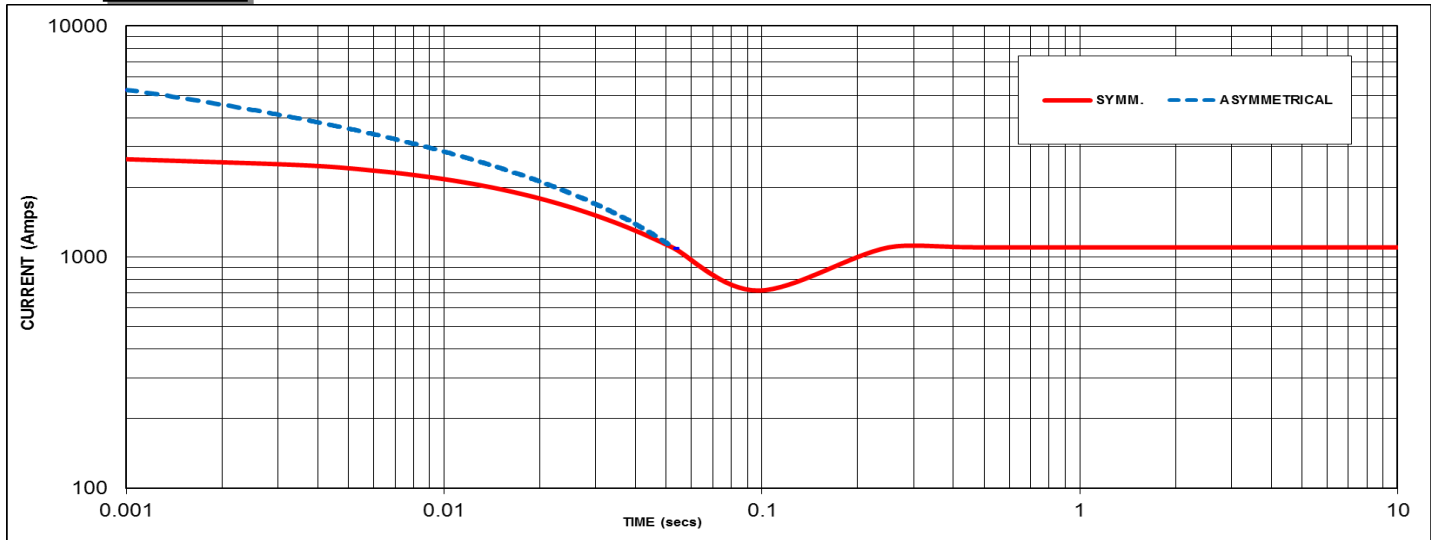
Transient Voltage Dip Scaling Factor		Transient Voltage Rise Scaling Factor
PF	Factor	
< 0.5	1	For voltage rise multiply voltage dip by 1.25
0.5	0.97	
0.6	0.93	
0.7	0.9	
0.8	0.85	
0.9	0.83	

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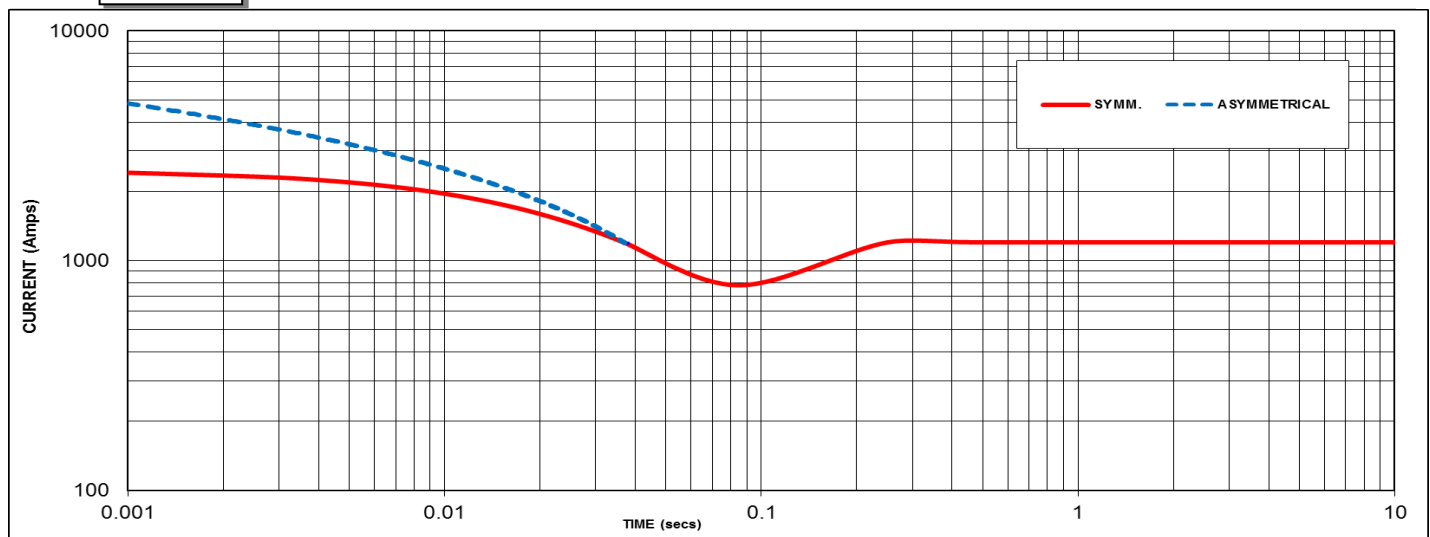
Three-phase Short Circuit Decrement Curve

50Hz



Sustained Short Circuit = 1100 Amps

60Hz



Sustained Short Circuit = 1200 Amps

Note 1

The following multiplication factors should be used to adjust the values from curve between time 0.001 seconds and the minimum current point in respect of nominal operating voltage :

50Hz		60Hz	
Voltage	Factor	Voltage	Factor
380V	X 1.00	416V	X 1.00
400V	X 1.05	440V	X 1.06
415V	X 1.09	460V	X 1.10
440V	X 1.16	480V	X 1.15

The sustained current value is constant irrespective of voltage level

Note 2

The following multiplication factor should be used to convert the values calculated in accordance with NOTE 1 to those applicable to the various types of short circuit :

	3-phase	2-phase L-L	1-phase L-N
Instantaneous	x 1.00	x 0.87	x 1.30
Minimum	x 1.00	x 1.80	x 3.20
Sustained	x 1.00	x 1.50	x 2.50
Max. sustained duration	10 sec.	5 sec.	2 sec.

All other times are unchanged

Note 3

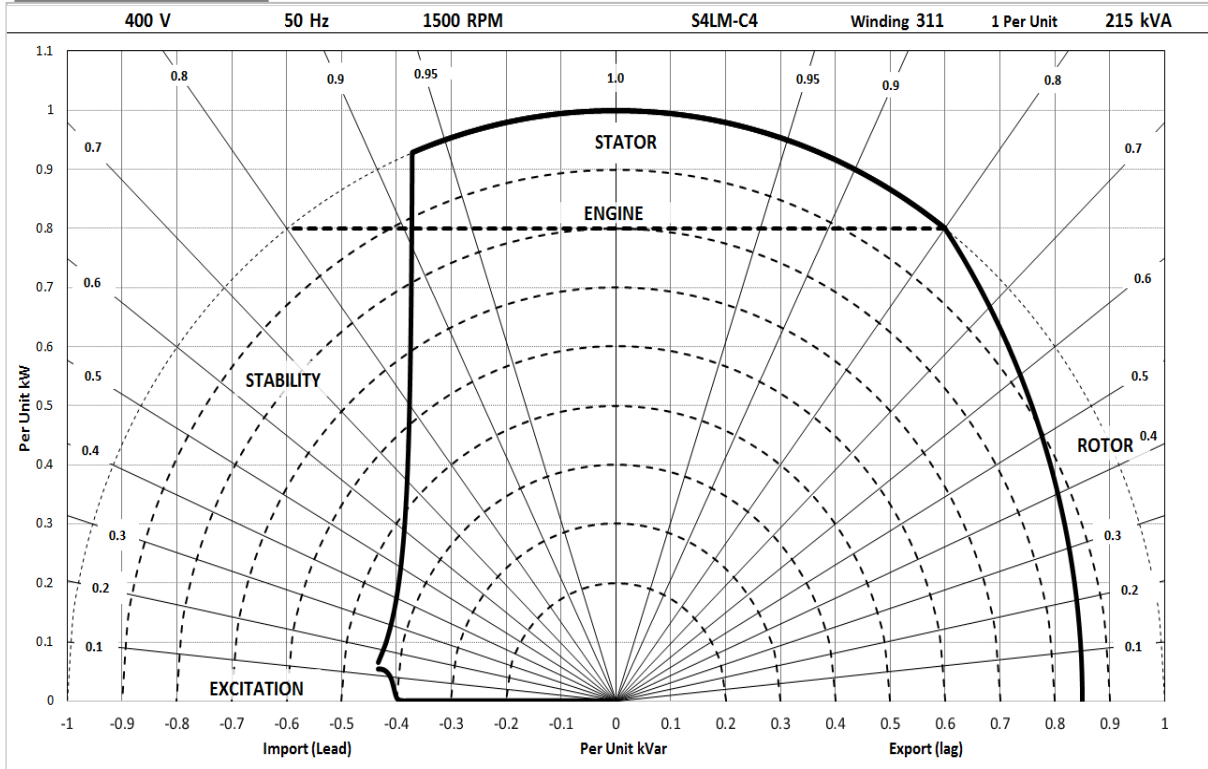
Curves are drawn for Star connected machines under no-load excitation at rated speeds. For other connection the following multipliers should be applied to current values as shown :
 Parallel Star = Curve current value X 2
 Series Delta = Curve current value X 1.732

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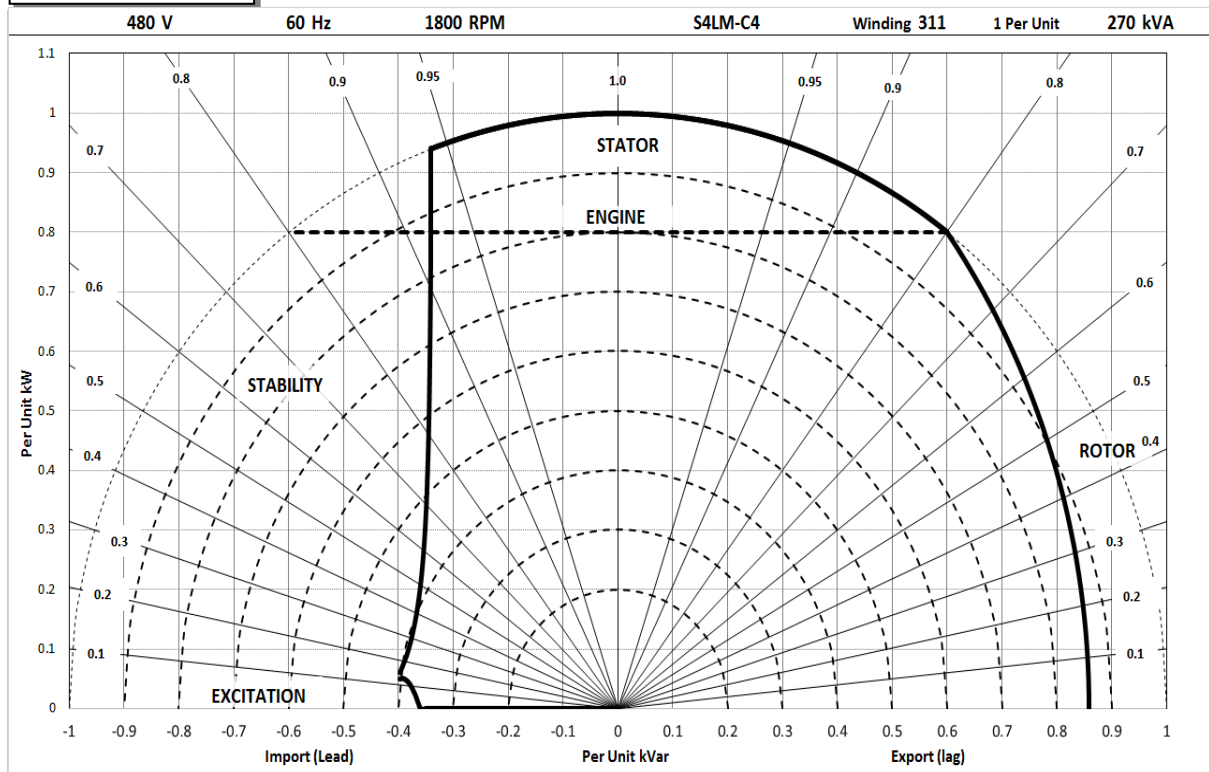
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Typical Alternator Operating Charts

400V/50Hz



480V/60Hz



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RATINGS AT 0.8 POWER FACTOR

Class - Temp Rise		Cont. E - 65/50°C				Cont. B - 70/50°C				Cont. F - 90/50°C				Cont. H - 110/50°C			
50 Hz	Series Star (V)	380	400	415	440	380	400	415	440	380	400	415	440	380	400	415	440
	kVA	175	175	175	175	185	185	185	185	210	210	210	210	215	215	215	215
	kW	140	140	140	140	148	148	148	148	168	168	168	168	172	172	172	172
	Efficiency (%)	93.8	93.9	94.0	94.0	93.7	93.8	93.9	94.0	93.3	93.5	93.6	93.8	93.2	93.4	93.6	93.7
	kW Input	149	149	149	149	158	158	158	157	180	180	179	179	185	184	184	184

60 Hz	Series Star (V)	416	440	460	480	416	440	460	480	416	440	460	480	416	440	460	480
	kVA	200	205	210	215	210	215	220	225	240	245	250	255	255	260	265	270
	kW	160	164	168	172	168	172	176	180	192	196	200	204	204	208	212	216
	Efficiency (%)	93.7	93.8	93.9	93.9	93.6	93.7	93.8	93.9	93.3	93.5	93.6	93.7	93.1	93.3	93.4	93.6
	kW Input	171	175	179	183	179	184	188	192	206	210	214	218	219	223	227	231

De-Rates

All values tabulated above are subject to the following reductions:

- 5% when air inlet filters are fitted
- 3% for every 500 meters by which the operating altitude exceeds 1000 meters above mean sea level
- 3% for every 5°C by which the operational ambient temperature exceeds 40°C
- For any other operating conditions impacting the cooling circuit please refer to applications

Note: Requirement for operating in an ambient exceeding 60°C and altitude exceeding 4000 meters must be referred to applications.

Dimensional and Torsional Drawing

For dimensional and torsional information please refer to the alternator General Arrangement and rotor drawings available on our website (<http://stamford-avk.com/>)

Note: Continuous development of our products means that the information contained in our data sheets can change without notice, and specifications should always be confirmed with Cummins Generator Technologies prior to purchase.



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